A New Index of Financial Conditions*

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Abstract

We use factor augmented vector autoregressive models with time-varying coefficients and stochastic volatility to construct a financial conditions index that can accurately track expectations about growth in key US macroeconomic variables. Time-variation in the model's parameters allows for the weights attached to each financial variable in the index to evolve over time. Furthermore, we develop methods for dynamic model averaging or selection which allow the financial variables entering into the financial conditions index to change over time. We discuss why such extensions of the existing literature are important and show them to be so in an empirical application involving a wide range of financial variables.

Keywords: Bayesian model averaging; dynamic factor model; dual Kalman filter; forecasting

JEL Classification: C11, C32, C52, C53, C66

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1 Introduction

The recent financial crisis has sparked an interest in the accurate measurement of financial shocks to the real economy. An important lesson of recent events is that financial developments, not necessarily driven by monetary policy actions or fundamentals, may have a strong impact on the economy. The need for policy-makers to closely monitor financial conditions is clear. In response to this need, a recent literature has developed several empirical econometric methods for constructing financial conditions indices (FCIs). FCIs are used for several purposes. For instance, they can be used to identify periods when financial conditions suddenly deteriorate (e.g., Lo Duca and Peltonen, 2013), assess credit constraints or forecast economic developments. An FCI summarizes in one single number information from many financial variables. Many financial institutions (e.g. Goldman Sachs, Deutsche Bank and Bloomberg) and policy-makers (e.g. the Federal Reserve Bank of Kansas City) produce closely-watched FCIs. Estimation of such FCIs ranges from using simple weighted averages of financial variables through more sophisticated econometric techniques. An important recent contribution is Hatzius, Hooper, Mishkin, Schoenholtz and Watson (2010) which surveys and compares a variety of different approaches. The FCI these authors propose is based on simple principal components analysis of a very large number of quarterly financial variables. Other recent notable studies in this literature include English, Tsatsaronis and Zoli (2005), Balakrishnan, Danninger, Elekdag and Tytell (2008), Beaton, Lalonde and Luu (2009), Brave and Butters (2011), Gomez, Murcia and Zamudio (2011) and Matheson (2011).

In this paper our goal is to accurately monitor financial conditions through a single latent FCI. The construction and use of an FCI involves three issues: i) selection of financial variables to enter into the FCI, ii) the weights used to average these financial variables into an index and iii) the relationship between the FCI and the macroeconomy. There is good reason for thinking all of these may be changing over time. Indeed, Hatzius et al (2010) discuss at length why such change might be occurring and document statistical instability in their results. For instance, the role of the sub-prime housing market in the financial crisis provides a clear reason for the increasing importance of variables reflecting the housing market in an FCI. A myriad of other changes may also impact on the way an FCI is constructed, including the change in structure of the financial industry (e.g. the growth of the shadow banking system), changes in the response of financial variables to changes in monetary policy (e.g. monetary policy works differently with interest rates near the zero bound) and the changing impact of financial variables on real activity (e.g. the role of financial variables in the recent recession is commonly considered to have been larger than in other recessions).

Despite such concerns about time-variation, the existing literature does little to statistically model it. Constant coefficient models are used with, at most, rolling
methods to account for time-variation. Furthermore, many FCI’s are estimated ex post, using the entire data set. So, for instance, at the time of the financial crisis, some FCIs will be based on financial variables which are selected after observing the financial crisis and the econometric model will be estimated using financial crisis data. The major empirical contribution of the present paper is to develop an econometric approach which allows for different financial variables to affect estimation of the FCI, with varying (or zero, when not selected) weight each. In this manner, we develop an econometric tool that explicitly takes into account the fact that each financial crisis has different causes, and is transmitted to the real economy with varying intensity.

Following a common practice in constructing indices, we use factor methods. To be precise, we use extensions of Factor-augmented VARs (FAVARs) which jointly model a large number of financial variables (used to construct the latent FCI) with key macroeconomic variables. Following the recent trend in macroeconomic modelling using VARs and FAVARs (Primiceri, 2005; Korobilis, 2013) we work with time-varying parameter FAVARs (TVP-FAVARs) which allow coefficients and loadings to change in each period. TVP-FAVARs have enjoyed increasing popularity for forecasting macroeconomic variables (see, among others, Eickmeier, Lemke and Marcellino, 2011a and D’Agostino, Gambetti and Giannone, 2013).

Additionally, we work with a large set of (TVP-) FAVARs that differ in which financial variables are included in the estimation of the FCI. Faced with a large model space and the desire to allow for model change, we follow Koop and Korobilis (2012) and use efficient methods for Dynamic Model Selection (DMS) and Dynamic Model Averaging (DMA). These methods forecast at each point in time with a single optimal model (DMS), or reduce the expected risk of the final forecast by averaging over all possible model specifications (DMA). We implement model selection or model averaging in a dynamic manner. That is, DMS chooses different financial variables to make up the FCI at different points in time. DMA constructs an FCI by averaging over many individual FCIs constructed using different financial variables. The weights in this average vary over time.

From an econometrician’s point of view, there is also growing theoretical evidence in favor of our modelling strategy. Boivin and Ng (2006) show that using all available data to extract factors (the FCI in our case) is not always optimal in factor analysis, thus providing support for implementing DMA/DMS to construct our FCI. Additionally, there is much econometric evidence in favor of structural instabilities in the coefficients or loadings of macroeconomic and financial factor models; see, among others, Banerjee, Marcellino and Masten (2006) and Bates, Plagborg-Møller, Stock and Watson (2013).

Econometric methods for estimating FAVARs and TVP-FAVARs are well-established; see, e.g., Bernanke, Boivin and Eliasz (2005), and Korobilis (2013). However, the likelihood-based estimation techniques used in the literature (e.g. Bayesian methods using Markov chain Monte Carlo algorithms) rely on simulation algorithms
or complex numerical methods, all of which are computationally demanding in high dimensions. With our large model space, and our wish to implement recursive forecasting, it is computationally infeasible to use such methods. Therefore, our major econometric contribution in this paper lies in the development of fast estimation methods which are based on the Kalman filter and smoother and are simulation-free. When dealing with the FAVAR with constant parameters, our algorithm collapses to the two-step estimator for dynamic factor models of Doz, Giannone and Reichlin (2011). In the case of estimating models with time-varying parameters and stochastic volatility (TVP-FAVARs), our algorithm provides an extension of Doz, Giannone and Reichlin (2011).

Our results indicate that financial variables do have predictive power for macroeconomic variables (GDP growth, inflation and unemployment) measured in real-time. The predictive ability of financial variables is stronger for nowcasts and short-term forecasts. Additionally, we find that time variation in the parameters is important for providing accurate short-run forecasts. In particular, we show that the contribution of stochastic (heteroskedastic) variances in the macroeconomic and financial variables is the most important source of time variation. Finally, model averaging and/or selection also result in the improvement of forecast accuracy over using a single model with all the available financial variables. In the remainder of the paper we examine all these issues in depth, and we provide evidence by using different forecast metrics and by conducting several robustness checks.

In particular, in the next section we introduce our modeling framework and sketch the features of our novel estimation algorithm (complete details are provided in the Technical Appendix), plus we describe how we implement DMA or DMS methods in the face of the large number of models we work with. In Section 3 we present our data, estimates of different FCIs, and results of a recursive forecasting exercise which is the main tool for evaluating the performance of our FCI. Section 4 concludes the paper. An empirical appendix provides an extensive sensitivity analysis to various aspects of our specification.

2 Factor Augmented VARs with Structural Instabilities

2.1 The TVP-FAVAR Model and its Variants

Let $x_t$ (for $t = 1, ..., T$) be an $n \times 1$ vector of financial variables to be used in constructing the FCI. Let $y_t$ be an $s \times 1$ vector of macroeconomic variables of interest. In our empirical work $y_t = (\pi_t, u_t, g_t)'$ where $\pi_t$ is the GDP deflator inflation rate, $u_t$ is the unemployment rate, $g_t$ is the growth rate of real GDP. The $p$-lag TVP-FAVAR
takes the form

\[
x_t = \lambda^y_t y_t + \lambda^f_t f_t + v_t
\]

\[
\begin{bmatrix}
  y_t \\
  f_t 
\end{bmatrix}
= c_t + B_{t,1} \begin{bmatrix}
  y_{t-1} \\
  f_{t-1}
\end{bmatrix} + \cdots + B_{t,p} \begin{bmatrix}
  y_{t-p} \\
  f_{t-p}
\end{bmatrix} + \varepsilon_t;
\]

where \( \lambda^y_t \) are regression coefficients, \( \lambda^f_t \) are factor loadings, \( f_t \) is the latent factor which we interpret as the FCI, \( c_t \) is a vector of intercepts, \( (B_{t,1}, \ldots, B_{t,p}) \) are VAR coefficients and \( u_t \) and \( \varepsilon_t \) are zero-mean Gaussian disturbances with time-varying covariances \( V_t \) and \( Q_t \), respectively. We adopt the common identifying assumption in the likelihood-based factor literature\(^1\) that \( V_t \) is diagonal, thus ensuring that \( v_t \) is a vector of idiosyncratic shocks and \( f_t \) contains information common to the financial variables. This model is very flexible since it allows all parameters to take a different value at each time \( t \). Such an assumption is important since there is good reason to believe that there is time variation in the loadings and covariances of factor models which use both financial and macroeconomic data (see Banerjee, Marcellino and Masten, 2006). For recent discussions about the implication of the presence of structural breaks in factor loadings, the reader is referred to Breitung and Eickmeier (2011) and Bates, Plagborg-Møller, Stock and Watson (2013).

Following the influential work of Bernanke, Boivin and Eliasz (2005) our factor model in (1) consists of two equations: one equation which allows us to extract the latent financial conditions index (FCI) from financial variables \( x_t \); and one equation which allows to model the dynamic interactions of the FCI with macroeconomic variables \( y_t \). This econometric specification is important for two reasons. First, unlike Stock and Watson (2002) who extract a factor and then use it in a separate univariate forecasting regression, we use a multivariate system to forecast macroeconomic variables using the FCI. Thus, we jointly model all the variables in the system which should allow us to better characterize their co-movements and interdependence. Second, we are able to purge from the FCI the effect of macroeconomic conditions. Thus, the final estimated FCI reflects information solely associated with the financial sector.

It is worth digressing to expand on the manner in which we include macroeconomic variables in our model. Including \( y_t \) on the right-hand side of the first equation of (1) is intended solely to ensure the FCI reflects only financial conditions. This is also done in Hatzius et al. (2010) for the same reason. However, it is worth stressing that, by doing this, we are only purging the FCI of the effect of current macroeconomic conditions. Financial variables can also reflect expectations of future macroeconomic variables and we are not purging the FCI of these future expectations. This is an issue common to all FCIs. As a robustness check, our empirical results (see Appendix C) also include a case where \( y_t \) in the first equation

\(^1\) Some approaches to dynamic factor models which do not use likelihood-based methods allow for weak correlations between the elements of \( v_t \).
of (1) is replaced by professional forecasts of macroeconomic variables (which reflect expectations of future macroeconomic conditions).

Including $y_t$ on the left-hand side of the second equation of (1) is done so as to provide a metric for evaluating our FCI. That is, in answer to the question: “what makes a good FCI?”, the approach in this paper provides the answer: “it is one which forecasts $y_t$ as well as possible”. There are, of course, other possible answers to this question which would lead to other FCIs. We are not attempting to build a structural model of the economy (e.g. a structural VAR or a DSGE) through the manner we are including $y_t$ in (1). Hence, issues which arise with structural models (e.g. structural VARs often involve an ordering of variables reflecting an assumed causal structure) do not need to be addressed here.

In order to complete our model, we need to define how the time varying parameters evolve. While the specification of all time-varying covariances is discussed in the following subsection, we define here the vectors of loadings $\lambda_t = \left(\lambda_t^0, \lambda_t^1\right)'$ and VAR coefficients $\beta_t = \left(c_t, \text{vec} (B_{t,p})', ..., \text{vec} (B_{t,p})''\right)'$ to evolve as multivariate random walks of the form

$$
\begin{align*}
\lambda_t &= \lambda_{t-1} + v_t, \\
\beta_t &= \beta_{t-1} + \eta_t,
\end{align*}
$$

where $v_t \sim N (0, W_t)$ and $\eta_t \sim N (0, R_t)$. Finally, all disturbance terms presented in the equations above are uncorrelated over time and with each other.

We call the full model described in equations (1) and (2) the TVP-FAVAR. We also consider several restrictions on the TVP-FAVAR which result in other popular multivariate models:

1. Factor-augmented VAR (FAVAR): This model is obtained from the TVP-FAVAR under the restriction that both $\lambda_t$ and $\beta_t$ are time-invariant ($W_t = R_t = 0$).

2. Time-varying parameter VAR (TVP-VAR): This model can be obtained from the TVP-FAVAR under the restriction that the number of factors is zero (i.e. $f_t = 0$).

3. VAR: This model is obtained when the number of factors is zero and both $\lambda_t$ and $\beta_t$ are time-invariant.

In addition, we consider heteroskedastic (when $V_t$ and $Q_t$ are allowed to be time-varying) and homoskedastic ($V_t = V$ and $Q_t = Q$) variants of all models.

### 2.2 Estimation of a Single TVP-FAVAR

Bayesian estimation of FAVARs (as well as VARs) with time-varying parameters is typically implemented using Markov Chain Monte Carlo (MCMC) methods, which
sample from the very complex multivariate joint posterior density of the factor $f_t$ and the remaining model parameters; see, e.g., Primiceri (2005), or Del Negro and Otrok (2008). Such Bayesian simulation methods are computationally expensive even in the case of estimating a single TVP-FAVAR. When faced with multiple TVP-FAVARs and when doing recursive forecasting (which requires repeatedly doing MCMC on an expanding window of data), the use of MCMC methods is prohibitive.\footnote{To provide the reader with an idea of approximate computer time, consider the three variable TVP-VAR of Primiceri (2005). Taking 10,000 MCMC draws (which may not be enough to ensure convergence of the algorithm) takes approximately 1 hour on a good personal computer. Thus, forecasting at 100 points in time takes roughly 100 hours. These numbers hold for a single small TVP-VAR, and would be much infeasible for the hundreds of thousands of larger TVP-FAVARs we estimate in this paper.}

In this paper, we use a fast two-step estimation algorithm which vastly reduces the computational burden, and greatly simplifies the estimation of the FCI. Following Koop and Korobilis (2013) we combine the ideas of variance discounting methods with the Kalman filter in order to obtain analytical results for the posteriors of the state variable $(f_t)$ as well as the time-varying parameters $\theta_t = (\lambda_t, \beta_t)$. To motivate our methods, note first that, as long as both the factor, $f_t$, and the loadings, $\lambda_t$, in the measurement equation are unobserved, application of the typical Kalman filter recursions for state-space models is not possible. Therefore, we adapt ideas from Doz, Giannone and Reichlin (2011) and the state-space literature (Nelson and Stear, 1976) and develop a dual, conditionally linear filtering/smoothing algorithm which allows us to estimate the unobserved state $f_t$ and the parameters $\theta_t = (\lambda_t, \beta_t)$ in a fraction of a second.

The idea of using a dual linear Kalman filter is very simple: first update the parameters $\theta_t$ given an estimate of $f_t$, and subsequently update the factor $f_t$ given the estimate of $\theta_t$. Such conditioning allows us to use two distinct linear Kalman filters or smoothers,\footnote{The other alternative being to use a joint nonlinear filter, e.g. the Unscented Kalman Filter (UKF) and the Extended Kalman Filter (EKF). We have found such filters to be very unstable given the dimension of our model, and the relatively few time-series observations.} one for $\theta_t$ and one for $f_t$. The main approximation involved is that $\tilde{f}_t$, the principal components estimate of $f_t$ based on $x_{1:t}$, is used in the estimation of $\theta_t$. Such an approach will work best if the principal component(s) provide a good approximation of the factor(s) coming from a FAVAR with structural instabilities. A theoretical proof that this is the case is not available for our flexible and highly nonlinear specification. However, given the recent findings of Stock and Watson (2009) and Bates, Plagborg-Møller, Stock and Watson (2013), there is strong theoretical and empirical evidence to believe that this is the case. Empirically, Bates, Plagborg-Møller, Stock and Watson (2013) conduct extensive Monte Carlo experiments and show that principal components can support large amount of time variation in the loading coefficients $\lambda_t$. Theoretically, they prove that principal component estimates of factors are consistent even if there is a substantial amount of time variation or structural change in the factor loadings. For instance, they
find that: “deviations in the factor loadings on the order of $o_p(1)$ [as would occur with random walk variation in the factor loadings] do not break the consistency of the principal components estimator” (page 290). This is the econometric theory we draw upon to justify use of principal components estimates at this stage in our algorithm.

Error covariance matrices in the multivariate time series models used with macroeconomic data are usually modeled using multivariate stochastic volatility models (see, e.g., Primiceri, 2005), estimation of which also requires computationally intensive methods. In order to avoid this computational burden, we estimate $(V_t, Q_t, W_t, R_t)$ recursively using simulation-free variance matrix discounting methods (e.g. Quintana and West, 1988). The Technical Appendix provides complete details. For $V_t$ and $Q_t$ we use exponentially weighted moving average (EWMA) estimators. These depend on decay factors $\kappa_1$ and $\kappa_2$, respectively. Such recursive estimators are trivial computationally. Additionally, the EWMA is an accurate approximation to an integrated GARCH model. Such a feature is in line with authors such as Primiceri (2005) and Cogley and Sargent (2005) who, in the context of macroeconomic VARs, work with integrated stochastic volatility models. The covariance matrices $W_t, R_t$ are estimated using the forgetting factor methods described in Koop and Korobilis (2012, 2013) which depend on forgetting factors $\kappa_3$ and $\kappa_4$, respectively. Decay and forgetting factors have very similar interpretations. Lower values of the decay/forgetting factors imply that the more recent observation $t - 1$, and its squared residual, take higher weight in estimating $V_t$ and $Q_t$ compared to older observations. The choice of the decay/forgetting factors can be made based on the expected amount of time-variation in the parameters. Note that the choice $\kappa_1 = \kappa_2 = 1$ make $V_t$ and $Q_t$ constant, while $\kappa_3 = \kappa_4 = 1$ imply that $W_t = R_t = 0$ in which case $\lambda_t$ and $\beta_t$ are constant.

A sketch of the structure of our estimation algorithm is given in the following:

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**Algorithm for estimation of the TVP-FAVAR**

1. a) Initialize all parameters, $\lambda_0, \beta_0, f_0, V_0, Q_0$
   
   b) Obtain the principal components estimates of the factors, $\tilde{f}_t$

2. Estimate the time varying parameters $\theta_t$ given $\tilde{f}_t$
   
   a) Estimate $V_t$, $Q_t$, $R_t$, and $W_t$ using VD

   b) Estimate $\lambda_t$ and $\beta_t$, given $(V_t, Q_t, R_t, W_t)$, using the KFS

3. Estimate the factors $f_t$ given $\theta_t$ using the KFS

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4An EWMA estimation scheme can also be applied to these matrices, but due to their large dimension we found better numerical stability and precision when using forgetting factors.

5Choice of forgetting factors is similar in spirit to choice of prior. Empirical macroeconomists frequently impose subjective priors on the degree of time variation in their parameters; see for instance the very informative priors used in the TVP-VARs of Primiceri (2005) and Cogley and Sargent (2005).
In the summary above, VD stands for “Variance Discounting” and KFS stands for “Kalman filter and smoother”. The steps above can also be considered to be a generalization of the estimation steps introduced by Doz et al. (2011) for the estimation of constant parameter dynamic factor models. In fact, if we fix all time-varying coefficients and covariances to be time-invariant, our algorithm collapses to the FAVAR equivalent of the two-step estimation algorithm for dynamic factor models of Doz et al. (2011).

Identification in the FAVAR is achieved in a standard fashion by restricting $V_t$ to be a diagonal matrix. This restriction ensures that the factors, $f_t$, capture movements that are common to the financial variables, $x_t$, after removing the effect of current macroeconomic conditions through inclusion of the $\lambda_t y_t$ term. Further restrictions usually imposed in likelihood-based estimation of factor models, e.g. normalizing the first element of the loadings matrix to be 1 (Bernanke, Boivin and Eliasz, 2005) are not needed here since the loadings $\lambda_t$ are identified (up to a sign rotation) from the principal components estimate of the factor.

2.3 Dynamic Model Averaging and Selection with many TVP-FAVARs

In this paper, we work with $M_{j}$, $j = 1, ..., J$, models which differ in the financial variables which enter the FCI. In other words, a specific model is obtained using the restriction that a specific combination of financial variables have zero loading on the factor at time $t$ or, equivalently, that different combinations of columns of $x_t$ are set to zero. Thus, $M_{j}$ can be written as

$$x_t^{(j)} = \lambda_t^{y(j)} y_t + \lambda_t^{f(j)} \beta_t^{(j)} + u_t^{(j)}$$

where $x_t^{(j)}$ is a subset of $x_t$, and $\beta_t^{(j)}$ is the FCI implied by model $M_{j}$. Since $x_t$ is of length $n$, there is a maximum of $2^n - 1$ combinations$^6$ of financial variables that can be used to extract the FCI.

When faced with multiple models, it is common to use model selection or model averaging techniques. However, in the present context we wish such techniques to be dynamic. That is, in a model selection exercise, we want to allow for the selected model to change over time, thus doing DMS. In a model averaging exercise, we want to allow for the weights used in the averaging process to change over time, thus leading to DMA. In this paper, we do DMA and DMS using an approach developed in Raftery et al (2010) in an application involving many TVP regression models. The reader is referred to Raftery et al (2010) for a complete derivation and motivation of DMA. Here we provide a general description of what it does.

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$^6$We remove from the model set the model with zero financial variables, i.e. with no FCI extracted.
The goal is to calculate \( \pi_{t|t-1,j} \) which is the probability that model \( j \) applies at time \( t \), given information through time \( t-1 \). Once \( \pi_{t|t-1,j} \) for \( j = 1, \ldots, J \) are obtained they can either be used to do model averaging or model selection. DMS arises if, at each point in time, the model with the highest value for \( \pi_{t|t-1,j} \) is used. Note that \( \pi_{t|t-1,j} \) will vary over time and, hence, the selected model can switch over time. DMA arises if model averaging is done in period \( t \) using \( \pi_{t|t-1,j} \) for \( j = 1, \ldots, J \) as weights. The contribution of Raftery et al (2010) is to develop a fast recursive algorithm for calculating \( \pi_{t|t-1,j} \).

Given an initial condition, \( \pi_{0|0,j} \) for \( j = 1, \ldots, J \), Raftery et al (2010) derive a model prediction equation using a forgetting factor:

\[
\pi_{t|t-1,j} = \frac{\pi_{t-1|t-1,j}^\alpha}{\sum_{l=1}^{J} \pi_{t-1|t-1,l}^\alpha},
\]

and a model updating equation of:

\[
\pi_{t|t,j} = \frac{\pi_{t|t-1,j} f_j(Data_t|Data_{1:t-1})}{\sum_{l=1}^{J} \pi_{t|t-1,l} f_l(Data_t|Data_{1:t-1})},
\]

where \( f_j(Data_t|Data_{1:t-1}) \) is a measure of fit for model \( j \). Many possible measures of fit can be used. Inspired by is a large literature (e.g., among many others, Forni, Hallin, Lippi and Reichlin, 2003) which investigate the ability of financial variables to forecast macroeconomic ones, we focus on the ability of the FCI to forecast \( y_t \). Accordingly, we set as a measure of fit the predictive likelihood for the macroeconomic variables, \( p_j(y_t|Data_{1:t-1}) \). \( \alpha \) is a forgetting factor with \( 0 < \alpha \leq 1 \) which, similar to the decay/forgetting factors \( (\kappa_1, \kappa_2, \kappa_3, \kappa_4) \) used for estimating the error covariance matrices, tunes how rapidly switches between models should occur. Lower values of \( \alpha \) allow for an increasing amount of switching between the number of variables that enter the FCI each time period. If \( \alpha = 0.99 \), forecast performance five years ago receives 80% as much weight as forecast performance last period. The case \( \alpha = 1 \) leads to conventional Bayesian model averaging implemented on an expanding window of data.

\(^7\)Throughout this paper past data up to time \( t \) will be denoted by \( 1 : t \) subscripts, e.g., \( Data_{1:t} = (Data_1, ..., Data_t) \).
3 Empirical Results

3.1 Data and Model Settings

We use 18 financial variables\textsuperscript{8} which cover a wide variety of financial considerations (e.g. asset prices, volatilities, credit, liquidity, etc.). These are gathered from several sources. All of the variables (i.e. both macroeconomic and financial variables) are transformed to stationarity following Hatzius et al (2010) and many others. The Data Appendix provides precise definitions, acronyms, data sources, sample spans and details about the transformations. Our data sample runs from 1970Q1 to 2013Q3. Notice that all of our models use four lags and, hence, the effective estimation sample begins in 1971Q1. The three macroeconomic variables that complete our model are the GDP deflator, the unemployment rate, and the real GDP. We use real time data such that forecasts are at time $t$ are always made using the vintage of data available at time $t$. All of these series are observed in real-time from 1970Q1, are seasonally adjusted, and can be found in the Real-Time Data Set for Macroeconomists provided by the Philadelphia Fed website. Macroeconomic variables which are not already in rates, that is the GDP deflator and real GDP, are converted to growth rates by taking first log-differences, which we will refer to as inflation and output growth, respectively.

Some of the financial variables have missing values in that they do not begin until much after 1970Q1. In terms of estimation with a single TVP-FAVAR model, such missing values cause no problem since they can easily be handled by the Kalman filter (see the Technical Appendix for more details). However, when we are using multiple models, there is a danger that in a specific model the value of the FCI in a period (say 1970Q1-1982Q1) has to be extracted using financial variables which all have missing values for that period. In such a case, the value of extracted FCI will be nil for the specified period, and the FCI will be estimated only after at least one variable becomes observed. We introduce a simple restriction to prevent such estimation issues. In each model, we always include the S&P500 in the list of financial variables, a variable which is observed since 1970Q1. This means that, at a minimum, the FCI will be extracted based on this financial variable. This restriction implies that the S&P500 is not subject to model averaging/selection and we instead perform DMA/DMS using the remaining 17 financial variables. Therefore, we have a model space of $2^{17}=131,072$ TVP-FAVARs. We remind the reader that a list of the different specifications estimated (and their acronyms) is given at the end of Section 2.1.

\textsuperscript{8}We have gathered a range of widely-used financial variables, following the recommendations of Hatzius et al. (2010). The final number of variables, though, was restricted by computational constraints. As we explain in the Technical Appendix, availability of computer clusters (such as the ones maintained by central banks, e.g. the ECB) could allow for the implementation of model averaging with many more variables.
To summarize, our models which produce an FCI are the TVP-FAVARs and the FAVARs. In our forecasting exercise, for the purpose of comparison, we also include some forecasting models which do not produce an FCI. These are the VARs and TVP-VARs. With these model spaces, we investigate the use of DMS, DMA and a strategy of simply using the single model which includes all 18 of the financial variables.

Some authors (e.g. Eickmeier, Lemke and Marcellino, 2011b) use existing FCIs (i.e. estimated by others) in the context of a VAR model. In this spirit, we also present results for VARs and TVP-VARs where the factors are not estimated from the factor model equation in (1), rather they are replaced with an existing estimate. To be precise, we use \((y_0, \hat{f}_t)\) as dependent variables for different choices of \(\hat{f}_t\). Table 1 lists these choices from a set of financial conditions and financial stress indices maintained by Federal Reserve Banks. Financial Stress indices (FSIs) are similar to FCIs, but have opposing signs: a decrease in financial conditions means increased financial stress, and vice-versa. However, FSIs tend to focus on different issues than FCIs. The latter tend to focus on broad measures of financial conditions, whereas FSIs narrowly focus on measuring instability in the financial system (i.e. the current level of frictions, stresses and strains). For this reason, we would argue that the Chicago Fed National FCI is the most comparable to the FCI we are producing in our empirical results. Again, these models are a restricted special case of our TVP-FAVAR and estimation proceeds accordingly. The error covariance matrix is modelled in the same manner as the TVP-FAVAR. We use an acronym for these TVP-VARs such that, e.g., TVP-VAR + FCI 4, is the VAR involving the three macroeconomic variables and the Chicago Fed National FCI.

<table>
<thead>
<tr>
<th>Name</th>
<th>Acronym</th>
<th>Source</th>
<th>Sample</th>
</tr>
</thead>
<tbody>
<tr>
<td>St. Louis Financial Stress Index</td>
<td>FCI 1</td>
<td>St Louis Fed</td>
<td>1993Q4 - 2012Q1</td>
</tr>
<tr>
<td>Kansas City Fed Financial Stress Index</td>
<td>FCI 2</td>
<td>Kansas Fed</td>
<td>1990Q1 - 2012Q1</td>
</tr>
<tr>
<td>Cleveland Fed Financial Stress Index</td>
<td>FCI 3</td>
<td>Cleveland Fed</td>
<td>1991Q3 - 2012Q1</td>
</tr>
<tr>
<td>Chicago Fed National FCI</td>
<td>FCI 4</td>
<td>Chicago Fed</td>
<td>1973Q1 - 2012Q1</td>
</tr>
</tbody>
</table>

3.2 Choice of hyperparameters and initial conditions

In this section we outline the setting of various hyperparameters and initial conditions. All our benchmark choices that apply in the next two subsections are fairly non-informative. In Appendix C we implement a sensitivity analysis using priors based on a training data sample, thus extending the recommendations of Primiceri (2005) to our TVP-FAVARs.

The first step is to set the initial conditions for the factor \(f_t\) (FCI), the time-varying parameters \(\lambda_t, \beta_t\), the time-varying covariances \(V_t, Q_t\), and, for doing DMA
and DMS, we must specify $\pi_{00,j}$, $j = 1, \ldots, J$. These initial conditions are set to the following (relatively non-informative) values

$$
\begin{align*}
    f_0 & \sim N(0, 4), \\
    \lambda_0 & \sim N(0, 4 \times I_{n(s+1)}), \\
    \beta_0 & \sim N(0, V_{MIN}) \\
    V_0 & \equiv 1 \times I_n, \\
    Q_0 & \equiv 1 \times I_{s+1}, \\
    \pi_{00,j} & = \frac{1}{J}
\end{align*}
$$

where $V_{MIN}$ is a diagonal covariance matrix which, following the Minnesota prior tradition, penalizes more distant lags and is of the form

$$
V_{MIN} = \begin{cases} 
4, & \text{for intercepts} \\
0.1/r^2, & \text{for coefficient on lag } r 
\end{cases}
$$

where $r = 1, \ldots, p$ denotes the lag number. Note that estimates of $W_t$ and $R_t$ are proportional to the respective state covariance matrices obtained from the Kalman filter, therefore there is no need to initialize these matrices; see the Technical Appendix for more details.

Regarding the decay and forgetting factors we have introduced in our model it is worth noting that we can estimate these from the data. However, computation increases substantially (we need to evaluate or maximize the predictive likelihood for each combination of the various factors) and, as shown in Koop and Korobilis (2013), the existence of value added in forecasting performance from such a procedure is questionable. Given these considerations, we choose to fix the values of the decay/forgetting factors, but investigate sensitivity to their choice in Appendix C.

For the decay factors $\kappa_1, \kappa_2$ which control the variation in the covariance matrices, we fix these to the value 0.96. Such values provide volatility estimates which are quite close to the ones expected by integrated stochastic volatility models that have been used extensively in the Bayesian VAR and FAVAR literature (Primiceri, 2005; Korobilis, 2013). For the forgetting factors $\kappa_3, \kappa_4$, we follow the “business as usual prior” approach of Cogley and Sargent (2005) and assume that changes each period are relatively slow and stable under the random walk specification in equation (2). In order to achieve this slow time variation in the coefficients, we set $\kappa_3 = \kappa_4 = 0.99$, a setting we use in all TVP-FAVAR and TVP-VAR specifications. As described in the Technical Appendix, restricted versions of our general model can be obtained by setting the forgetting factors to one. For instance when $\kappa_3 = \kappa_4 = 1$, we obtain the VAR model.

Finally, we need to choose our prior beliefs about model change. The value of the forgetting factor $\alpha$ determines how fast model switches occur, and thus we
use two values: $\alpha = 1$ which implies that we are implementing Bayesian model averaging (BMA) given data up to time $t$; and $\alpha = 0.99$ which implies that we implement dynamic model averaging (DMA) with relatively slowly varying model probabilities.

### 3.3 Estimates of the Financial Conditions Index

Before we proceed to the forecasting exercise, it is important to understand how both our estimation algorithm and model averaging work in the context of estimating an FCI. The results in this section are recursive. That is the estimate of the FCI at time $t$ is made using data up to time $t$.

Figure 1 shows the FCI estimated in various ways using all 18 financial variables without any model selection or model averaging being done. The shaded regions in this figure (and subsequent figures) are the NBER recession dates. The estimated FCIs are all similar to each other. In particular, the TVP-FAVAR and principle components are producing very similar FCIs. The FCI produced by the FAVAR does differ from the others at some points, particularly in the first half of the sample. This indicates the potential importance of allowing for time variation in parameters. It is interesting to note that the FCIs start declining before the beginning of the recent recession with all of them bottoming out in early 2009. However, after 2009 some discrepancies appear between the FCIs.

Figure 2 shows the impact of model averaging and selection on the estimate of the FCI, focussing on the TVP-FAVARs. Although the broad patterns in the FCIs plotted in Figure 2 are similar, there are some differences. In general, the FCIs in Figure 2 are less smooth than in Figure 1 indicating that model switching/averaging is reacting more quickly than methods without such a feature. And there are some interesting small divergences between the two figures. For instance, in Figure 2 there is a slight improvement in the FCIs early on in the recent recession which is missing from Figure 1. DMA and DMS are producing factor estimates which are very similar to one another.

In Figure 3 we perform a comparison of the FCI constructed using DMA on the TVP-FAVAR models with the four FCIs or FSIs maintained by four Federal Reserve Banks (see Table 1). As discussed previously, FCIs and FSIs are somewhat different since FSIs are measuring financial stress (and, hence, it is the comparison of our approach with the Chicago Fed’s National Financial Conditions Index which is the most relevant). We have multiplied the FSIs by minus one to maintain comparability with the FCIs. Additionally, we standardize all the indices to have mean zero and variance one. Our FCI does indeed match up most closely with the Chicago Fed’s FCI. Our FCI started dropping earlier than the Chicago Fed’s in 2008 and dropped to a lower value at the depth of the current recession. In contrast, after the 2001 recession ended, our FCI grew faster and peaked at a higher level than the Chicago Fed’s. However, there are substantive differences with the FSIs. It is interesting to
note that, after this 2001 recession ended, the FSIs continued to signal deteriorating financial conditions for much longer than our FCI. In general, the FSIs (in particular, the Cleveland Fed’s FCI) exhibit substantively different behavior from our FCI.

Figures 1 through 3 compare a range of different FCI estimates. At this stage, we express no view on whether any FCI is better or worse than any other. The key finding we stress is that, although they are similar to one another in many respects, differences can occur. These differences are most notable when we compare our TVP-FAVAR based estimates to conventional estimates produced by Federal Reserve Banks.

Figure 1. FCIs constructed from several versions of the heteroskedastic factor-augmented VAR model with all 18 financial variables used (no model averaging/selection). For comparison, the principal component of the 18 financial variables is also plotted.
Figure 2. FCIs implied by BMA, DMA and DMS on the TVP-FAVARs (with DMA results for FAVARs provided for comparison)

Figure 3. The FCI from the TVP-FAVAR with DMA compared to existing financial indexes maintained by four regional US central banks.

To provide some additional insight on what DMA is doing, we present Figures 4 and 5 which shed light on the number of variables selected when we do DMA
or DMS on the TVP-FAVARs. In particular, Figure 4 calculates the expected number of variables used to extract the FCI at each point in time. If we denote by $n_j$ the number of variables which load on the FCI under model $M_j$, then we calculate each time period the following expectation$^9$

$$E \left( n_t^{DMA} \right) = \left( \sum_{j=1}^{J} \pi_{t|t,j} \times n_j \right) - 1.$$ 

Figure 4 shows DMA or DMS is achieving a strong degree of parsimony. Given 17 variables to choose between, it is tending to choose between 5 and 8. There is a slow decrease in the number of variables chosen until the late 90s, then there was an abrupt increase until the current recession. Interestingly, in the middle of the recent recession, the number of variables selected started dropping again before stabilizing at the end of the recession.

Figure 4. Average number of variables used to extract the FCI at each point in time as implied by DMA applied in the full TVP-FAVAR specification.

Figure 5 provides evidence on which variables receive most weight in the DMA procedure (or are selected by DMS). The numbers in each panel of this figure are the total probability DMA attaches to models which contain the variable named in the title on the panel. It is worth noting that there is substantial variable switching. That is, there are a few variables which enter then leave (or vice versa) the FCI.

$^9$We subtract one since the S&P500 variable is always included in all models.
Figure 5. Time-varying probabilities of inclusion to the final FCI for each of the 18 financial variables (S&P500 is always included; see Section 3.1). Zero probabilities at the beginning of the sample for some of the variables correspond to periods of missing observations.

3.4 Forecasting

In this section, we investigate the performance of a wide range of models and methods for forecasting inflation, output growth and the unemployment rate. Our forecast evaluation period is 1990Q1 through 2013Q3 for \( h = 0, 1, 2, 3, 4 \) quarters ahead. Note that, since we are using real-time data, it is also informative to present nowcasts and these are labelled \( h = 0 \) in the tables. Evaluation of forecast accuracy is based on the mean squared forecast error (MSFE) and average of predictive likelihoods (APL). The former evaluates the quality of point forecasts whereas the latter evaluates the quality of the entire predictive distribution. Results are normalized by dividing an MSFE or APL by the corresponding value produced by a benchmark model. We use a homoskedastic VAR (with no FCI) as our benchmark model. To be precise, at time \( t \) (given delays in release of macroeconomic variables) we have macroeconomic data available through period \( t - 1 \). This is used to provide nowcasts \((h = 0)\) and forecasts \((h = 1, \ldots, 4)\) using iterative methods.
benchmark. For this benchmark model, the table presents the actual value of MSFE or APL. Details of our choices of forgetting and decay factors are given in Section 2 and we investigate the sensitivity of results to their choice in Appendix C. The notation in the table (and the tables in Appendix C) extends our previous notation. Thus, TVP-FAVAR indicates the TVP-FAVAR with all 18 financial variables whereas TVP-FAVAR-DMA uses DMA (with \( \alpha = 0.99 \)) over the \( 2^{17} \) TVP-FAVARs. Notation such as TVP-FAVAR \((c_1, c_2)\) means that we set \( \kappa_1 = \kappa_2 = c_1 \) and \( \kappa_3 = \kappa_4 = c_2 \). We also present results for a VAR containing the macroeconomic variables plus a factor estimated using principle components (labelled VAR+PC). As another simple comparator, we also produce OLS (diffuse prior Bayesian) forecasts from AR models augmented with a factor (estimated by principal components). At each point in time, we choose the lag length which has produced the lowest MSFE over the last 40 quarters. From this model, we present recursive (labelled AR+PC(rec)) and rolling (labelled AR+PC(rol)) forecasts. For the rolling forecasts, we try windows of 25, 30, 35 and 40 periods and present results for the one which produces the lowest MSFE over the last 40 quarters.

For the MSFEs we also present the Bayesian variant of a test of forecast accuracy developed in Diebold and Mariano (1995). This test is described in Appendix B of Garratt et al (2009). If an MSFE in the table has a *, it means the approach forecasts significantly differently from the benchmark VAR.

Table 2 is organized so that each panel begins with a standard benchmark (e.g. the homoskedastic VAR), then adds heteroskedasticity (e.g. the TVP-VAR(0.96, 1) which selects the forgetting factor so as to make the VAR coefficients constant over time but allows for heteroskedasticity), then adds time variation in coefficients (e.g. the TVP-VAR(0.96, 0.99)). Then the next panel in the table repeats the process with models which include FCIs beginning with the FAVAR. The subsequent panel investigates the usefulness of DMA or DMS.

In general, Table 2 shows a pattern where forecasts improve as we add in extensions. Adding heteroskedasticity tends to improve forecasts substantially, then adding time-variation in parameters tends to improve them a bit more. Moving from TVP-VARs to TVP-FAVARs leads to further improvements in forecast performance. Using DMA or DMS with the \( 2^{17} \) TVP-FAVARs leads to yet further improvements. Of course, there are some exceptions to this pattern. Table 2 investigates forecasting performance for three variables at five different horizons using two different forecast evaluation metrics. With so many possible forecast evaluations it is not surprising there are some cases where simpler approaches beat our more complicated TVP-FAVAR-DMS or TVP-FAVAR-DMA approaches. But overall the latter are tending to produce the best forecasts.

Another important pattern in Table 2 is that our approach (again with some

---

\( ^{11} \)This VAR is obtained as the restricted special case of the TVP-FAVAR (i.e. dropping the equation for the factors and turning off the variation in coefficients). Thus, its prior is equivalent to the prior for the initial conditions of the TVP-VAR described in Section 3.2.
exceptions) tends to forecast much better than standard approaches, including the VAR, the FAVAR and simple univariate methods. The simple univariate methods occasionally forecast well (e.g. when forecasting unemployment a year ahead, the recursive AR model forecasts well when MSFE is used as a forecasting metric and AR+PC(rol) often forecasts inflation well), but often forecast very badly. In contrast, the approaches involving TVP-FAVARs and DMA or DMS typically forecast best and never forecast badly. They also virtually always beat FAVARs, indicating the importance of allowing for time-variation in parameters.
<table>
<thead>
<tr>
<th>Forecast Metric</th>
<th>APL</th>
<th>MSFE</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>h = 0</td>
<td>h = 1</td>
</tr>
<tr>
<td><strong>Inflation</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>VAR (no FCI)</td>
<td>0.8587</td>
<td>0.7470</td>
</tr>
<tr>
<td>TVP-VAR (0.96,1)</td>
<td>1.36</td>
<td>1.31</td>
</tr>
<tr>
<td>TVP-VAR (0.96,0.99)</td>
<td>1.35</td>
<td>1.32</td>
</tr>
<tr>
<td><strong>Unemployment</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>VAR (no FCI)</td>
<td>0.6508</td>
<td>0.4119</td>
</tr>
<tr>
<td>TVP-VAR (0.96,1)</td>
<td>1.47</td>
<td>1.52</td>
</tr>
<tr>
<td>TVP-VAR (0.96,0.99)</td>
<td>1.48</td>
<td>1.49</td>
</tr>
<tr>
<td><strong>Output</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>VAR (no FCI)</td>
<td>0.3380</td>
<td>0.3170</td>
</tr>
<tr>
<td>TVP-VAR (0.96,1)</td>
<td>1.38</td>
<td>1.41</td>
</tr>
<tr>
<td>TVP-VAR (0.96,0.99)</td>
<td>1.35</td>
<td>1.38</td>
</tr>
</tbody>
</table>
| Notes: APL is the average predictive likelihood (not in logarithms), and MSFE is the mean squared forecast error. Model's forecast performance is better when APL (MSFE) is higher (lower). For each variable (inflation, unemployment, output) the first line shows the APL and MSFE of the benchmark model for each forecast horizon h. All other models' APL and MSFE are relative to that of the benchmark model. Values of APL (MSFE) higher (lower) than 1 signify better performance than the benchmark.
Also of interest is the performance of our approach relative to VAR forecasts augmented with an existing FCI. Before doing so, we note that such comparisons are extremely difficult since different indices are based on different assumptions, data transformations, frequencies and sample sizes. The earliest common starting date for the FCIs is 1994Q1 and, accordingly, we re-estimate our models using data from this point and use 2000Q1 - 2013Q3 as our forecast evaluation period. Table 1 describes the existing FCIs and FSIs and defines the acronyms we use in Table 3. We use the same naming convention as in Table 2 so that, for instance, TVP-VAR+FCI4 is the TVP-VAR which includes the macroeconomic variables and the Chicago Fed National FCI. All modelling choices (e.g. priors and discount factors) are the same benchmark choices as those used previously (see Section 3.2).

In relation to the approach developed in this paper, the story is similar to that told by Table 2. TVP-FAVARs with DMA or DMS still are either the best or among the best forecasting models for all the macroeconomic variables at all forecasting horizons. The table also shows that substantial benefits can be achieved by allowing for time-variation in parameters and doing DMA or DMS. Among the existing FCIs, use of the Chicago Fed's National FCI tends to lead to the best forecasting performance. Given the fact that it is this FCI which is most similar to our own (see Figure 3), it is not surprising that the TVP-VAR which includes FCI4 is providing forecasting results similar to our TVP-FAVAR which includes all of the financial variables. Nevertheless, it is worth noting that DMA or DMS do add additional improvements in forecast performance so that TVP-FAVAR-DMA and TVP-FAVAR-DMS almost always forecast better than the TVP-VAR-FCI4.

Including any of the FSIs (i.e. FCI1, FCI2 or FCI3) in a TVP-VAR usually leads to fairly good forecast performance, but rarely as good as FCI4. And there are some cases where these other existing indices forecast poorly. For instance, the Kansas City Fed's FSI forecasts of unemployment are appreciably worse than those of other indices.
<table>
<thead>
<tr>
<th></th>
<th><strong>INFLATION</strong></th>
<th><strong>UNEMPLOYMENT</strong></th>
<th><strong>OUTPUT</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$h = 0$</td>
<td>$h = 1$</td>
<td>$h = 2$</td>
</tr>
<tr>
<td><strong>VAR (no FCI)</strong></td>
<td>0.8713</td>
<td>0.7572</td>
<td>0.7175</td>
</tr>
<tr>
<td><strong>VAR + PC</strong></td>
<td>0.98</td>
<td>1.00</td>
<td>1.00</td>
</tr>
<tr>
<td><strong>VAR + FCI1</strong></td>
<td>0.91</td>
<td>0.93</td>
<td>0.90</td>
</tr>
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<td><strong>VAR + FCI2</strong></td>
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<td><strong>VAR + FCI3</strong></td>
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<td>0.97</td>
<td>0.97</td>
</tr>
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<td><strong>VAR + FCI4</strong></td>
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</tr>
<tr>
<td><strong>TVP-VAR + FCI1</strong></td>
<td>1.16</td>
<td>1.16</td>
<td>1.18</td>
</tr>
<tr>
<td><strong>TVP-VAR + FCI2</strong></td>
<td>1.22</td>
<td>1.27</td>
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</tr>
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<td><strong>TVP-VAR + FCI3</strong></td>
<td>1.30</td>
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<tr>
<td><strong>TVP-VAR + FCI4</strong></td>
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<tr>
<td><strong>FAVAR</strong></td>
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<td>1.00</td>
<td>1.00</td>
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<td><strong>TVP-FAVAR</strong></td>
<td>1.27</td>
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<td><strong>TVP-FAVAR-DMA</strong></td>
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<td><strong>TVP-FAVAR-DMS</strong></td>
<td>1.36</td>
<td>1.39</td>
<td>1.44</td>
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<tr>
<td><strong>TVP-FAVAR-BMA</strong></td>
<td>1.37</td>
<td>1.34</td>
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<td><strong>TVP-FAVAR-BMS</strong></td>
<td>1.37</td>
<td>1.38</td>
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<tr>
<td><strong>AR + PC (rec)</strong></td>
<td>1.02</td>
<td>1.10</td>
<td>1.09</td>
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<tr>
<td><strong>AR + PC (rol)</strong></td>
<td>1.03</td>
<td>1.68</td>
<td>1.78</td>
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<tr>
<td><strong>AR + FCI1 (rec)</strong></td>
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<td>1.03</td>
<td>1.01</td>
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<td><strong>AR + FCI1 (rol)</strong></td>
<td>1.16</td>
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<td><strong>AR + FCI2 (rec)</strong></td>
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<td>1.29</td>
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<td><strong>AR + FCI4 (rol)</strong></td>
<td>1.33</td>
<td>1.49</td>
<td>1.44</td>
</tr>
</tbody>
</table>
Table 3b: Performance of our FCI compared to other FCIs: relative MSFEs, 2000Q1 - 2013Q3

<table>
<thead>
<tr>
<th></th>
<th>INFLATION</th>
<th>UNEMPLOYMENT</th>
<th>OUTPUT</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>h = 0</td>
<td>h = 1</td>
<td>h = 2</td>
</tr>
<tr>
<td>VAR (no FCI)</td>
<td>0.0602</td>
<td>0.0744</td>
<td>0.0767</td>
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<tr>
<td>VAR + PC</td>
<td>1.04</td>
<td>0.99</td>
<td>0.98</td>
</tr>
<tr>
<td>VAR + FCI1</td>
<td>1.19</td>
<td>1.11</td>
<td>1.18</td>
</tr>
<tr>
<td>VAR + FCI2</td>
<td>1.01</td>
<td>0.92*</td>
<td>0.95</td>
</tr>
<tr>
<td>VAR + FCI3</td>
<td>1.09</td>
<td>1.06</td>
<td>1.11</td>
</tr>
<tr>
<td>VAR + FCI4</td>
<td>1.16</td>
<td>1.09</td>
<td>0.97</td>
</tr>
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<td>VAR + FCI5</td>
<td>1.05</td>
<td>0.91*</td>
<td>0.83*</td>
</tr>
<tr>
<td>TVP-VAR (no FCI)</td>
<td>0.87*</td>
<td>0.76*</td>
<td>0.80*</td>
</tr>
<tr>
<td>TVP-VAR + PC</td>
<td>0.89*</td>
<td>0.76*</td>
<td>0.75*</td>
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<tr>
<td>TVP-VAR + FCI1</td>
<td>1.12</td>
<td>1.07</td>
<td>0.95*</td>
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<td>TVP-VAR + FCI2</td>
<td>1.09</td>
<td>0.85*</td>
<td>0.77*</td>
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4 Conclusions

In this paper, we have argued for the desirability of constructing a dynamic financial conditions index which takes into account changes in the financial sector, its interaction with the macroeconomy and data availability. In particular, we want a methodology which can choose different financial variables at different points in time and weight them differently. We develop DMS and DMA methods, adapted from Raftery et al. (2010) and others, to achieve this aim. Using a large data set of US macroeconomic and financial variables, we find our estimated FCI to have reasonable properties. It is broadly similar to existing FCIs, but does exhibit some interesting differences.

We also demonstrate the usefulness of our FCI as a forecasting tool. Working with a large model space involving many TVP-FAVARs which make different choices of financial variables, we find DMA and DMS methods lead to improved forecasts of macroeconomic variables, relative to methods which use a single model. We also show the importance of allowing for time variation in parameters and heteroskedasticity in achieving good forecast performance. The largest improvements come from the presences of time variation in the model parameters (in particular the volatilities). However, there are also improvements from also allowing the model space to vary over time, by means of DMA and DMS.

This paper opens new avenues for research in factor models. We have documented in the Introduction an increased interest of the literature in factor methods with structural instabilities, and we have thus provided a very simple and feasible solution to the problem of estimating a complex time-varying parameter factor-augmented VAR (TVP-FAVAR) model. A question of interest is how accurate our estimation methods are, and whether they can be improved. For instance, one can follow the novel ideas in Doz et al. (2011) and iterate our two-step algorithms several more times in order to increase estimation accuracy. Such algorithmic issues are examined in detail in Korobilis and Schumacher (2014), where the authors also examine efficient Bayesian schemes for covariance matrix estimation other than simple exponential weighted moving average (EWMA) filter we use in this paper.
References


