# Inference on higher-order spatial autoregressive models with increasingly many parameters 

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#### Abstract

This paper develops consistency and asymptotic normality of parameter estimates for a higher-order spatial autoregressive model whose order, and number of regressors, are allowed to approach infinity slowly with sample size. Both least squares and instrumental variables estimates are examined, and the permissible rate of growth of the dimension of the parameter space relative to sample size is studied. Besides allowing the number of parameters to increase with the data, this has the advantage of accommodating some asymptotic regimes that are suggested by certain spatial settings, several of which are discussed. A small empirical example is also included, and a Monte Carlo study analyses various implications of the theory in finite samples.


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## 1. Introduction

Correlation in cross-sectional data poses considerable challenges, complicating both modelling and statistical inference. When information on geographical locations is available, it may be possible to extend models developed for time series data. However, when locations are irregularly-spaced serious difficulties arise, and frequently only information on economic (not necessarily geographic) distances is available. Spatial autoregressive (SAR) models, due to Cliff and Ord (1973), have become widely used in this setting. Given a sample of size $n$, these employ a known $n \times n$ spatial weights matrix whose $(i, j)$ th element is inversely related to some measure of economic distance between units $i$ and $j$. The elements may also be binary, for instance taking equal values 1 when two units are contiguous and 0 otherwise, but many other specifications are possible.

To be specific, for an $n \times 1$ vector of observations $y_{n}$, an $n \times k$ matrix of regressors $X_{n}$ and $n \times n$ weight matrices $W_{i n}, i=1, \ldots, p$,

[^0]it is assumed that there exist unknown scalars $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{p}$ and an unknown $k \times 1$ vector $\beta$ such that
$y_{n}=\sum_{i=1}^{p} \lambda_{i} W_{i n} y_{n}+X_{n} \beta+U_{n}$,
where $U_{n}$ is an $n \times 1$ vector of disturbances. This model, allowing $p>1$, has been studied by, e.g., Blommestein (1983), Huang (1984), Huang and Ahn (1992), Anselin (2001), Lee and Liu (2010) and Badinger and Egger (2013). In this paper we will refer to the above as the SAR model while the SAR model without $X_{n}$ will be the pure SAR model.

Weight matrices need not be symmetric and can contain negative elements, but their diagonal elements are zero, and they are frequently row-normalized such that each row sums to 1 . If $W_{\text {in }}$ has non-negative elements, this implies that its $(j, l)$ th element can be interpreted as $w_{j l, \text { in }}=d_{j l, \text { in }} / \sum_{h=1}^{n} d_{j h, \text { in }}$, where $d_{j l, \text { in }}$ measures inverse distance between units $j$ and $l$. Thus elements of the $W_{i n}$ are allowed to depend on $n$, so those of $y_{n}$ form a triangular array. Since $X_{n}$ may also depend on spatial weights, we also allow its elements to depend on $n$. See e.g. Arbia (2006) for a review of spatial autoregressions.

By far the most popular version of (1.1) takes $p=1$, when we write
$y_{n}=\lambda W_{n} y_{n}+X_{n} \beta+U_{n}$.
Due to the spatially lagged $y_{n}$ on the right, ordinary least squares (OLS) estimation of $\lambda$ and $\beta$ is problematic, but Lee (2002) showed that under suitable conditions OLS can be consistent, and asymptotically normal and efficient. In particular, for a divergent positive sequence $h_{n}$ that is bounded away from zero uniformly in $n$, consistency follows if $w_{i j, n}=\mathscr{O}\left(h_{n}^{-1}\right)$ and asymptotic normality if also $n^{\frac{1}{2}} / h_{n} \rightarrow 0$ as $n \rightarrow \infty$.

Instrumental variables (IV) estimation (see Kelejian and Prucha (1998)) is $n^{\frac{1}{2}}$-consistent under less restrictive conditions than OLS, but inefficient. On the other hand, it is computationally simpler than procedures which may have better statistical properties, such as generalized method of moments (Kelejian and Prucha, 1999; Lee and Liu, 2010), optimal IV (Lee, 2003), Gaussian pseudo maximum likelihood (Lee, 2004), and adaptive estimation (Robinson, 2010). Additionally, desirable asymptotic properties of OLS and IV require $X_{n}$ to contain at least one non-intercept regressor.

In this paper we allow the spatial lag order $p$ in (1.1) and the number of regressors $k$ to increase slowly with $n$, as opposed to being fixed. This scheme reflects the practical reality that the richness of a parametric model often deepens with sample size, and has been explored previously in various settings. The model studied in this paper is defined explicitly in the next section.

Higher-order SAR models (such that $p>1$ in (1.1)) raise serious identifiability problems, which become more acute if $p$ is allowed to increase with $n$. Our assumptions for consistency and asymptotic normality imply identifiability, but the practitioner needs to be aware of what choices of the $W_{i n}$ can potentially afford it. It is obvious that no $W_{\text {in }}$ can be a linear combination of the others, but this property is far from sufficient (see e.g. Anselin (2001)). One particular class of $W_{\text {in }}$ will transparently avoid identifiability problems, in particular ones with 'single nonzero diagonal block structure'. To define these, denote by $V_{n}$ an $n \times n$ block diagonal matrix with $i$ th block $V_{i n}$, a $m_{i} \times m_{i}$ matrix, where $\sum_{i=1}^{p} m_{i}=n$, and for $i=1, \ldots, p$ obtain $W_{i n}$ from $V_{n}$ by replacing each $V_{j n}, j \neq i$, by a matrix of zeros. Thus $V_{n}=\sum_{i=1}^{p} W_{i n}$.

This structure can be thought of as extending a choice of $W_{n}$ in (1.2) suggested by Case (1991, 1992), where each of $p$ districts contains $m$ farmers, so $n=m p$, and there is interdistrict independence, implying a block diagonal $W_{n}$, and also homogeneous within-district reactions, so
$W_{n}=I_{p} \otimes B_{m}, \quad$ with $B_{m}=(m-1)^{-1}\left(l_{m} l_{m}^{\prime}-I_{m}\right)$,
where prime denotes transposition, $l_{m}$ is the $m$-dimensional vector of ones $(1, \ldots, 1)^{\prime}, I_{m}$ is the $m$-dimensional identity matrix and $\otimes$ denotes Kronecker product. For (1.1) we might then take the $W_{\text {in }}$ to have single nonzero diagonal block structure such that
$m_{i}=m, \quad V_{i n}=B_{m}, \quad i=1, \ldots, p$,
allowing SAR coefficients to vary across districts. In asymptotic theory for (1.1) using (1.3), $p$ is sometimes allowed to diverge with $n$, and if that happens with (1.4) the number of possibly distinct $\lambda_{i}$ likewise increases. Of course (1.4) might then be extended to allow unequal $m_{i}$ and $V_{i n}$ across $i$, and $V_{i n}$ with more complex structure. As in the statistical literature on regression models, we also allow $k$ to increase slowly with $n$. This theme has been pursued in a variety of models (see e.g. Huber, 1973; Berk, 1974; Robinson, 1979, 2003; Portnoy, 1984, 1985), but not previously with SAR models. Pinkse et al. (2002) consider nonparametric series estimation of a model with spatial weights determined by an unknown function of economic distances.

The following section introduces some assumptions that are basic to our theoretical results. Further assumptions, and theorems, for the consistency and asymptotic normality of IV and OLS estimates are presented in Sections 3 and 4 respectively. In Section 5 we consider some illustrations, followed by an empirical example in Section 6. We conduct a Monte Carlo study in Section 7, while Section 8 concludes. Proofs are in Appendices A and B

## 2. Model and basic assumptions

We rewrite (1.1) to stress the possible dependence of the parameter dimension, and the parameters themselves, on $n$ and also introduce an endogenous regression component:
$y_{n}=\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n} y_{n}+H_{n} \gamma_{(n)}+X_{n} \beta_{(n)}+U_{n}$,
where $\lambda_{(n)}=\left(\lambda_{1 n}, \ldots, \lambda_{p_{n} n}\right)^{\prime}, \gamma_{(n)}=\left(\gamma_{1 n}, \ldots, \gamma_{s_{n} n}\right)^{\prime}$ and $\beta_{(n)}=$ $\left(\beta_{1 n}, \ldots, \beta_{k_{n} n}\right)^{\prime}$. We may write (2.1) as
$S_{n} y_{n}=H_{n} \gamma_{(n)}+X_{n} \beta_{(n)}+U_{n}$,
where $S_{n}=I_{n}-\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n}$, or equivalently $y_{n}=R_{n} \lambda_{(n)}+$ $H_{n} \gamma_{(n)}+X_{n} \beta_{(n)}+U_{n}$ with $R_{n}=\left(W_{1 n} y_{n}, \ldots, W_{p_{n} n} y_{n}\right) . X_{n}$ will be taken to comprise exogenous elements, while $s_{n}$ can also diverge and the elements of $H_{n}$ are allowed to be correlated with $u_{n}$. We now introduce some basic assumptions.

Assumption 1. $U_{n}=\left(u_{1}, \ldots, u_{n}\right)^{\prime}$ has iid elements with zero mean and finite variance $\sigma^{2}$.

Assumption 2. For $i=1, \ldots, p_{n}$, the diagonal elements of each $W_{i n}$ are zero and the off-diagonal elements of $W_{i n}$ are uniformly $\mathscr{O}\left(h_{n}^{-1}\right)$, where $h_{n}$ is some positive sequence which is bounded away from zero and which may be bounded or divergent, with $n / h_{n} \rightarrow \infty$ as $n \rightarrow \infty$.
Different $h_{i n}$ sequences for each of the $W_{\text {in }}$ may be used. However for OLS estimation, even for fixed $p$, Lee (2002) demonstrated that consistency requires divergence so that $\min _{i=1, \ldots, p_{n}} h_{i n} \rightarrow$ $\infty$ must be assumed. He also provided a detailed discussion of this assumption. In IV estimation, any mixture of bounded and divergent $h_{i n}$ sequences may be employed. Boundedness away from zero is crucial as even consistency of the error variance estimate based on IV residuals may fail if this does not hold, Indeed, in the 'farmer-district' setting discussed in the previous section, $h_{n}=m-1$.

Assumption 3. $S_{n}$ is non-singular for sufficiently large $n$.
This assumption ensures that (2.2) has a solution for $y_{n}$. In certain special cases such as the farmer-district setting presented above, a sufficient condition can be provided for Assumption 3. For any $s \times q$ matrix $A=\left[a_{i j}\right]$ we define $\|A\|_{R}=\max _{i=1, \ldots, s} \sum_{j=1}^{q}\left|a_{i j}\right|$, the maximum absolute row-sum norm. The proof of the following can be found in the Appendix.

Proposition 2.1. When for each $i=1, \ldots, p_{n},\left\|W_{\text {in }}\right\|_{R} \leq 1$ and each $W_{\text {in }}$ has a single nonzero diagonal block structure, a sufficient condition for invertibility of $S_{n}$ is that $\left|\lambda_{i n}\right|<1, i=1, \ldots, p_{n}$.
Assumption 4. $\left\|S_{n}^{-1}\right\|_{R},\left\|S_{n}^{\prime-1}\right\|_{R},\left\|W_{i n}\right\|_{R}$ and $\left\|W_{\text {in }}^{\prime}\right\|_{R}$ are bounded uniformly in $n$ and $i, i=1, \ldots, p_{n}$, for sufficiently large $n$.
This assumption is standard, the parts pertaining to $S_{n}^{-1}$ ensuring that the spatial correlation is curtailed to a manageable degree because the covariance matrix of $y_{n}$ conditional on the regressors is $\sigma^{2} S_{n}^{-1} S_{n}^{\prime-1}$, while those for the $W_{\text {in }}$ are satisfied trivially if one unit is assumed to be a 'neighbour' of only a finite number of other units, and more generally satisfied if, for each $i$, the elements of $W_{\text {in }}$ decline fast enough with $n$, as is natural if they are inverse distances.

## 3. Instrumental variables estimates

Because of endogeneity of the $W_{i n} y_{n}, i=1, \ldots, p_{n}$, IV estimation has been employed for estimation of SAR models, and we also introduce instruments for the endogenous component $H_{n}$. Let $Z_{n}$ be an $n \times r_{n}$ matrix of instruments, with $r_{n} \geq p_{n}+s_{n}$ for all $n$. For (1.2), Kelejian and Prucha (1998) noted that $W_{n} \mathbb{E}\left(y_{n}\right)$ can be written as an infinite linear combination of the columns of the matrices $X_{n}, W_{n} X_{n}, W_{n}^{2} X_{n}, W_{n}^{3} X_{n}, \ldots$, assuming the existence of a convergent power series for $\left(I_{n}-\lambda W_{n}\right)^{-1}$. The existence of such a series is guaranteed if any matrix norm of $\lambda W_{n}$ is less than 1 (see e.g. Kreyszig (2011), pg. 398). It was suggested that the part of the instrument matrix pertaining to the spatially lagged $y_{n}$ be constructed from linearly independent subsets of the columns of $X_{n}, W_{n} X_{n}, W_{n}^{2} X_{n}, \ldots, W_{n}^{j} X_{n}$, for some $j \geq 1$. Our theory allows the number of instruments $r_{n}$ to increase with $n$.

Write $\bar{\eta}(B)$ (respectively $\eta(B)$ ) for the largest (smallest) eigenvalue of a square, symmetric matrix $B$. For a rectangular matrix $A$, define the spectral norm $\|A\|=\left\{\bar{\eta}\left(A^{\prime} A\right)\right\}^{\frac{1}{2}}$. For the specification (2.1) with $\gamma_{(n)}=0$,
$\mathbb{E}\left(y_{n}\right)=S_{n}^{-1} X_{n} \beta_{(n)}=\left[\sum_{k=0}^{\infty}\left(\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n}\right)^{k}\right] X_{n} \beta_{(n)}$,
assuming that the power series is well-defined, for which a sufficient condition is

$$
\begin{equation*}
\left\|\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n}\right\|<1 \tag{3.2}
\end{equation*}
$$

For example, (1.4) implies $\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n}=\operatorname{diag}\left(\lambda_{1 n} B_{m}, \lambda_{2 n} B_{m}, \ldots\right.$, $\lambda_{p_{n} n} B_{m}$ ), so that $\left\|\sum_{i=1}^{p_{n}} \lambda_{i n} W_{i n}\right\| \leq \max _{i=1, \ldots, p_{n}}\left|\lambda_{i n}\right|\left\|B_{m}\right\| . B_{m}$ has one eigenvalue equal to 1 and also $-1 /(m-1)$ as an eigenvalue with multiplicity $m-1$. Hence $\left\|B_{m}\right\|=1$ and $\max _{i=1, \ldots, p_{n}}\left|\lambda_{i n}\right|<1$ suffices for (3.2). See also Proposition 2.1 for a similar result. If (3.1) is indeed valid, instruments may be constructed as subsets of the linearly independent columns of

$$
\begin{align*}
& X_{n}, W_{1 n} X_{n}, W_{1 n}^{2} X_{n}, \ldots, W_{2 n} X_{n}, W_{2 n}^{2} X_{n}, \ldots, W_{p_{n} n} X_{n} \\
& \quad W_{p n n}^{2} X_{n}, \ldots \tag{3.3}
\end{align*}
$$

Columns of $X_{n}$ pre-multiplied by cross-products of the $W_{\text {in }}$ may also be employed in view of (3.1). Other choices of instruments from outside the model may be available to the practitioner, who will also need to find instruments for $H_{n}$.

Denoting $\theta_{(n)}=\left(\lambda_{(n)}^{\prime}, \gamma_{(n)}^{\prime}, \beta_{(n)}^{\prime}\right)^{\prime}$, define the IV estimate of $\theta_{(n)}$ as
$\hat{\theta}_{(n)}=n^{-1} \overline{\bar{Q}}_{n}^{-1} \overline{\bar{K}}_{n}^{\prime} \bar{J}_{n}^{-1}\left[Z_{n}, X_{n}\right]^{\prime} y_{n}=\theta_{(n)}+\overline{\bar{Q}}_{n}^{-1} \overline{\bar{K}}_{n}^{\prime} \bar{J}_{n}^{-1} q_{n}$,
where $\overline{\bar{Q}}_{n}=\overline{\bar{K}}_{n}^{\prime} \bar{J}_{n}^{-1} \overline{\bar{K}}_{n}$ (dimension $p_{n}+s_{n}+k_{n}$ ) and $\overline{\bar{K}}_{n}=n^{-1}$ $\left[Z_{n}, X_{n}\right]^{\prime}\left[R_{n}, H_{n}, X_{n}\right]$ (dimension $\left.\left(r_{n}+k_{n}\right) \times\left(p_{n}+s_{n}+k_{n}\right)\right), \bar{J}_{n}=$ $n^{-1}\left[Z_{n}, X_{n}\right]^{\prime}\left[Z_{n}, X_{n}\right]$ (dimension $r_{n}+k_{n}$ ), $q_{n}=n^{-1}\left[Z_{n}, X_{n}\right]^{\prime} U_{n}$. Assumption 3 implies that $y_{n}=S_{n}^{-1} H_{n} \gamma_{(n)}+S_{n}^{-1} X_{n} \beta_{(n)}+S_{n}^{-1} U_{n}$, so $R_{n}=A_{n}+B_{n}$ where $A_{n}=\left[G_{1 n}\left(H_{n} \gamma_{(n)}+X_{n} \beta_{(n)}\right), \ldots, G_{p_{n} n}\right.$ $\left.\left(H_{n} \gamma_{(n)}+X_{n} \beta_{(n)}\right)\right], B_{n}=\left[G_{1 n} U_{n}, \ldots, G_{p_{n} n} U_{n}\right]$ and $G_{i n}=W_{i n} S_{n}^{-1}$ for $i=1, \ldots, p_{n}$. Also define $\bar{K}_{n}=n^{-1}\left[Z_{n}, X_{n}\right]^{\prime}\left[A_{n}, H_{n}, X_{n}\right], \bar{Q}_{n}=$ $\bar{K}_{n}^{\prime} \bar{J}_{n}^{-1} \bar{K}_{n}, \bar{L}_{n}=n^{-1}\left[A_{n}, H_{n}, X_{n}\right]^{\prime}\left[A_{n}, H_{n}, X_{n}\right]$ (dimension $p_{n}+s_{n}+$ $k_{n}$ ). Write, respectively, $a_{i n}^{\prime}, p_{i n}$ and $a_{i j, n}$ for the $i$ th row, $i$ th column and a typical element of $\left[Z_{n}, X_{n}\right]$, and $z_{i n}$ for the $i$ th column of $Z_{n}^{\prime}$. Let $C$ denote a generic, arbitrarily large positive constant that is independent of $n$.

Assumption 5. $X_{n}$ and $z_{i n}$ are independent of $u_{i}, i=1, \ldots, n$, and $\max _{1 \leq i \leq n, 1 \leq j \leq r_{n}+k_{n}} \mathbb{E} a_{i j, n}^{2}<C$.

The elements of the instrument matrix corresponding to spatial lags typically contain elements from different rows of $X_{n}$ by construction, hence the independence requirement on all of $X_{n}$. The assumption implies $\mathbb{E}\left\|a_{i n}\right\|^{2}=\mathscr{O}\left(r_{n}+k_{n}\right)$ and $\mathbb{E}\left\|p_{i n}\right\|^{2}=\mathscr{O}(n)$, uniformly in $i$.
Assumption 6. As $n \rightarrow \infty, \bar{\eta}\left(\bar{J}_{n}\right)=\mathscr{O}_{p}(1)$ and $\left\{\underline{\eta}\left(\bar{K}_{n}^{\prime} \bar{K}_{n}\right)\right\}^{-1}=$ $\mathscr{O}_{p}(1)$.
Assumption 7. As $n \rightarrow \infty,\left\{\underline{\eta}\left(\bar{J}_{n}\right)\right\}^{-1}=\mathscr{O}_{p}(1)$ and $\bar{\eta}\left(\bar{K}_{n}^{\prime} \bar{K}_{n}\right)=$ $\mathscr{O}_{p}(1)$.
These are asymptotic non-multicollinearity and boundedness conditions, which can to some extent be checked. For instance, if $X_{n}$ contains a column of ones (i.e. (2.1) has an intercept), for a row-normalized $W_{i n}$ with equal off-diagonal elements (such as (1.4)) $W_{i n} y_{n}$ is asymptotically collinear with the intercept. In this case the second part of Assumption 6 fails, and in fact so does Assumption 12, introduced later. This problem is discussed further in Kelejian and Prucha (2002). However this does not preclude inclusion of an intercept, as the identification conditions may in fact hold if weight matrices are not row-normalized. A necessary condition for both Assumption 12 and $\left\{\underline{\eta}\left(\bar{K}_{n}^{\prime} \bar{K}_{n}\right)\right\}^{-1}=\mathscr{O}_{p}(1)$ to hold is that, for all $i=1, \ldots, p_{n}, W_{i n}$ are linearly independent for sufficiently large $n$, failing which some of the $\lambda_{\text {in }}$ are not identified.

Lemma 3.1. Under Assumptions 6 and 7 respectively, as $n \rightarrow \infty$,
(i) $\left\{\underline{\eta}\left(\bar{Q}_{n}\right)\right\}^{-1}=\mathscr{O}_{p}(1)$.
(ii) $\bar{\eta}\left(\bar{Q}_{n}\right)=\mathscr{O}_{p}(1)$.

Theorem 3.1. Let Assumptions 1-6 hold and
$\frac{1}{p_{n}}+\frac{1}{r_{n}}+\frac{1}{s_{n}}+\frac{1}{k_{n}}+\frac{p_{n}\left(r_{n}+k_{n}\right)}{n} \rightarrow 0 \quad$ as $n \rightarrow \infty$.
Then
$\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\| \xrightarrow{p} 0, \quad$ as $n \rightarrow \infty$.
Condition (3.5) details the restrictions on the growth of the numbers of instruments and regressors, and implies a restriction on the growth of the parameter space because $p_{n}+s_{n} \leq r_{n}$. The theorem also holds when $r_{n}$ (therefore $p_{n}$ and $s_{n}$ ) and/or $k_{n}$ are fixed, with (3.5) being altered to exclude reference to the fixed quantity. Slightly weakened conditions yield the same result for the just identified case $p_{n}+s_{n}=r_{n}$, where $\overline{\bar{K}}_{n}$ and $\bar{K}_{n}$ are square matrices so that $\hat{\theta}_{(n)}=n^{-1} \overline{\bar{K}}_{n}^{-1}\left[Z_{n}, X_{n}\right]^{\prime} y_{n}$ and $\bar{Q}_{n}^{-1}=\bar{K}_{n}^{-1} \bar{J}_{n} \bar{K}_{n}^{\prime-1}$.

Corollary 3.2. Let $p_{n}+s_{n}=r_{n}$, Assumptions $1-5$ hold, and let
$\left\{\underline{\eta}\left(\bar{K}_{n}^{\prime} \bar{K}_{n}\right)\right\}^{-1}=\mathscr{O}_{p}(1)$,
and
$\frac{1}{p_{n}}+\frac{1}{s_{n}}+\frac{1}{k_{n}}+\frac{p_{n}\left(p_{n}+s_{n}+k_{n}\right)}{n} \rightarrow 0 \quad$ as $n \rightarrow \infty$.
Then
$\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\| \xrightarrow{p} 0, \quad$ as $n \rightarrow \infty$.
A natural estimate of $\sigma^{2}$ is
$\hat{\sigma}_{(n)}^{2}=n^{-1}\left\|y_{n}-\left[R_{n}, X_{n}\right] \hat{\theta}_{(n)}\right\|^{2}$.

Assumption 8. As $n \rightarrow \infty, \bar{\eta}\left(\bar{L}_{n}\right)=\mathscr{O}_{p}(1)$.
Theorem 3.2. Let Assumptions 1-6 and 8 hold, and
$\frac{1}{p_{n}}+\frac{1}{r_{n}}+\frac{1}{s_{n}}+\frac{1}{k_{n}}+\frac{\left(p_{n}+s_{n}+k_{n}\right)\left(r_{n}+k_{n}\right)}{n} \rightarrow 0 \quad$ as
$n \rightarrow \infty$.
Then
$\hat{\sigma}_{(n)}^{2} \xrightarrow{p} \sigma^{2}$ as $n \rightarrow \infty$.

A similar theorem holds in the just identified case $p_{n}+s_{n}=$ $r_{n}$ but we omit the statement for brevity. Here the requirement that $h_{n}$ be bounded away from zero is crucial (see (A.7)), with consistency possibly failing otherwise. We can also record a central limit theorem for finitely many arbitrary linear combinations of $\hat{\theta}_{(n)}-\theta_{(n)}$ under stronger conditions which restrict the growth of $p_{n}$ and $r_{n}$ relative to $n$ further.

Assumption 9. $n^{-1} \max _{1 \leq i \leq n}\left\|a_{i n}\right\|^{2} \xrightarrow{p} 0$ as $n \rightarrow \infty$.
This is a standard kind of requirement for a Lindeberg condition to hold. In particular if $Z_{n}$ and $X_{n}$ have uniformly bounded nonstochastic elements, it is satisfied if $r_{n}+k_{n}=o(n)$.

Assumption 10. There exist constant matrices $K_{n}$ and $J_{n}\left(J_{n}\right.$ symmetric) satisfying $\underline{\lim }_{n \rightarrow \infty} \underline{\eta}\left(K_{n}^{\prime} K_{n}\right)>0, \overline{\lim }_{n \rightarrow \infty} \bar{\eta}\left(K_{n}^{\prime} K_{n}\right)<\infty$, $\underline{\lim }_{n \rightarrow \infty} \underline{\eta}\left(J_{n}\right)>0$ and $\overline{\lim }_{n \rightarrow \infty} \bar{\eta}\left(J_{n}\right)<\infty$, such that $\left(r_{n}+k_{n}\right)^{\frac{1}{2}}$ $\left(\left\|\bar{K}_{n}-\bar{K}_{n}\right\|,\left\|\bar{J}_{n}-J_{n}\right\|\right)=o_{p}(1)$, as $n \rightarrow \infty$.

We define $Q_{n}=K_{n}^{\prime} J_{n}^{-1} K_{n}$, and note that $\overline{\lim }_{n \rightarrow \infty} \bar{\eta}\left(Q_{n}\right)<\infty$ and $\underline{\lim }_{n \rightarrow \infty} \underline{\eta}\left(Q_{n}\right)>0$ can be shown using Assumption 10, as in Lemma 3.1. The presence of $X_{n}$ in both $Z_{n}$ and $A_{n}$ makes it difficult to establish elementwise laws of large numbers (or stochastic orders) for the matrices inside norms, but we illustrate the restriction imposed by the rate above using the bound derived in (A.2) in Appendix A as an example of a rate for the norm of a matrix of increasing dimension in the context of this paper. Indeed, $\left(r_{n}+k_{n}\right)^{\frac{1}{2}}\left\|\overline{\bar{K}}_{n}-\bar{K}_{n}\right\|=\mathscr{O}_{p}\left(p_{n}^{\frac{1}{2}}\left(r_{n}+k_{n}\right) / n^{\frac{1}{2}}\right)$, which would be negligible under (3.10) below. Another example is found in the familiar $X_{n}^{\prime} X_{n} / n$ block. If the rows $X_{i n}^{\prime}$ of $X_{n}$ are iid with elements having finite fourth moments, then $\left(r_{n}+k_{n}\right)^{\frac{1}{2}}\left\|X_{n}^{\prime} X_{n} / n-\mathbb{E} x_{i n} x_{\text {in }}^{\prime}\right\|=$ $\mathscr{O}_{p}\left(\left(r_{n}+k_{n}\right)^{\frac{1}{2}} k_{n}^{\frac{1}{2}} / n^{\frac{1}{2}}\right)$, which is again negligible under (3.10). Denote by $\Psi_{n}$ a generic $q \times\left(p_{n}+k_{n}\right)$ matrix of constants with full row-rank.

Theorem 3.3. Let Assumptions $1-10$ hold and

$$
\begin{equation*}
\frac{1}{p_{n}}+\frac{1}{r_{n}}+\frac{1}{s_{n}}+\frac{1}{k_{n}}+\frac{p_{n}\left(r_{n}^{2}+k_{n}^{2}\right)}{n}+\frac{\left(k_{n}+s_{n}\right)\left(r_{n}+k_{n}\right)}{n} \rightarrow 0 \tag{3.10}
\end{equation*}
$$

as $n \rightarrow \infty$.
Then
$\frac{n^{\frac{1}{2}}}{\left(p_{n}+s_{n}+k_{n}\right)^{\frac{1}{2}}} \Psi_{n}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right) \xrightarrow{d} N\left(0, \Xi_{1}\right), \quad$ as $n \rightarrow \infty$,
where $\Xi_{1}=\sigma^{2} \lim _{n \rightarrow \infty}\left(p_{n}+s_{n}+k_{n}\right)^{-1} \Psi_{n} Q_{n}^{-1} \Psi_{n}^{\prime}$, which may be consistently estimated by $\hat{\sigma}_{(n)}^{2}\left(p_{n}+s_{n}+k_{n}\right)^{-1} \Psi_{n} \overline{\bar{Q}}_{n}^{-1} \Psi_{n}^{\prime}$.

Corollary 3.3. Let $p_{n}+s_{n}=r_{n}$, Assumptions 1-5, 7-10, (3.6) hold and

$$
\begin{align*}
& \frac{1}{p_{n}}+\frac{1}{s_{n}}+\frac{1}{k_{n}}+\frac{p_{n}^{3}}{n}+\frac{p_{n}\left(s_{n}^{2}+k_{n}^{2}\right)}{n}+\frac{s_{n} k_{n}}{n} \rightarrow 0 \\
& \quad \text { as } n \rightarrow \infty \tag{3.11}
\end{align*}
$$

Then
$\frac{n^{\frac{1}{2}}}{\left(p_{n}+s_{n}+k_{n}\right)^{\frac{1}{2}}} \Psi_{n}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right) \xrightarrow{d} N\left(0, \Xi_{2}\right) \quad$ as $n \rightarrow \infty$,
where $\Xi_{2}=\sigma^{2} \lim _{n \rightarrow \infty}\left(p_{n}+s_{n}+k_{n}\right)^{-1} \Psi_{n} K_{n}^{-1} J_{n} K_{n}^{\prime-1} \Psi_{n}^{\prime}$, which may be consistently estimated by $\hat{\sigma}_{(n)}^{2}\left(p_{n}+s_{n}+k_{n}\right)^{-1} \Psi_{n} \overline{\bar{K}}_{n}^{-1} \bar{J}_{n}$ $\overline{\bar{K}}_{n}^{\prime-1} \Psi_{n}^{\prime}$.

Note that in Theorem 3.3 the condition $p_{n} r_{n}^{2} / n \rightarrow 0$ implies $p_{n} k_{n}^{2} / n \rightarrow 0$ so long as $k_{n}=\mathscr{O}\left(r_{n}\right)$ i.e. the number of regressors increases no faster than the number of instruments. In particular if $r_{n}$ is fixed (implying that $p_{n}$ and $s_{n}$ are fixed), $k_{n}=\mathscr{O}\left(r_{n}\right)$ is not satisfied unless $k_{n}$ is also fixed. Similarly $r_{n} k_{n} / n \rightarrow 0$ implies $k_{n}^{2} / n \rightarrow 0$ if $k_{n}=\mathscr{O}\left(r_{n}\right)$.

The $n^{\frac{1}{2}} /\left(p_{n}+s_{n}+k_{n}\right)^{\frac{1}{2}}$-norming is needed to ensure a finite asymptotic covariance matrix, and implies slower than $n^{\frac{1}{2}}$-consistency due to the growing parameter space dimension, while conditions (3.10) and (3.11) restrict the growth. Indeed, if only $n^{\frac{1}{2}}$-norming was employed the rows of $\Psi_{n}$ would have to be assumed to have uniformly bounded norm, which implies a similar normalization as these rows have increasing dimension. The norming can change if the rows of $\Psi_{n}$ contain many zero elements, indeed the number of nonzero elements can even be allowed to increase at a rate slower than the rate of increase of the parameters. In particular, Theorem 3.3 may be easily rewritten if the interest is in obtaining a central limit theorem for a fixed number of the parameters rather than an increasing number. If we are interested in the first $l$ elements of $\theta_{(n)}$, we may take $\Psi_{n}$ to be a $1 \times\left(p_{n}+k_{n}\right)$ non-null row vector with all elements after the $l$ th entry equal to zero. We then recover a $n^{\frac{1}{2}}$-consistency result which indicates that the behaviour of simple $t$-statistics does not change from the fixeddimension model (1.1) to (2.1).

Corollary 3.4. (i) Let Assumptions $1-10$ and (3.10) hold. Then

$$
n^{\frac{1}{2}}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)_{l} \xrightarrow{d} N\left(0, \sigma^{2} \Omega_{1}^{l}\right), \text { as } n \rightarrow \infty,
$$

where $\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)_{l}$ denotes the first $l$ elements of $\hat{\theta}_{(n)}-\theta_{(n)}$ while the limiting top-left $l \times l$ block of $Q_{n}^{-1}$ is denoted $\Omega_{1}^{l}$.
(ii) Let $p_{n}+s_{n}=r_{n}$, Assumptions 1-5, 7-10, (3.6) and (3.11) hold. Then

$$
n^{\frac{1}{2}}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)_{l} \xrightarrow{d} N\left(0, \sigma^{2} \Omega_{2}^{l}\right), \quad \text { as } n \rightarrow \infty
$$

where $\Omega_{2}^{l}$ denotes the limiting top-left $l \times l$ block of $K_{n}^{-1} J_{n} K_{n}^{\prime-1}$. The asymptotic covariance matrices are estimated as in Theorem 3.3.
The setting of Case $(1991,1992)$ was discussed in Section 1 as a natural motivation for the work in this paper. From an applied point of view a parsimonious model may be desirable, and so some districts can be allowed to have the same $\lambda_{i}$ on the basis of some homogeneity e.g. geography or demographics. There are other reasons to allow for a slower increase of the $\lambda_{i}$ than with $p$. For instance, in this setting the condition $p_{n}^{3} / n \rightarrow 0$ (keeping $k_{n}$ fixed for simplicity) translates to $p^{2} / m \rightarrow 0$. For finite samples an approximation to this would be that the ratio $p^{2} / m$ be small, but
this may not be reasonable if, say, $p=10$ and $m=100$. It would be natural then to allow a slower increase of the parameter space than $p$, and attempts can be made to combine some $\lambda_{i}$ to reduce the ratio $p^{2} / m$. Section 7 illustrates the behaviour of estimates in this setting.

## 4. Least squares estimates

The model we consider in this section is (2.1) without the endogenous component $H_{n}$. Redefine $\theta_{(n)}=\left(\lambda_{(n)}^{\prime}, \beta_{(n)}^{\prime}\right)^{\prime}$, and define its OLS estimate
$\tilde{\theta}_{(n)}=n^{-1} \overline{\bar{L}}_{n}^{-1}\left[R_{n}, X_{n}\right]^{\prime} y_{n}=\theta_{(n)}+\overline{\bar{L}}_{n}^{-1} w_{n}$,
where $\overline{\bar{L}}_{n}=n^{-1}\left[R_{n}, X_{n}\right]^{\prime}\left[R_{n}, X_{n}\right], \quad w_{n}=n^{-1}\left[R_{n}, X_{n}\right]^{\prime} U_{n}$. Note that in the context of this section $\bar{L}_{n}=n^{-1}\left[A_{n}, X_{n}\right]^{\prime}\left[A_{n}, X_{n}\right]$. Write $t_{i n}^{\prime}, m_{i n}$ and $t_{i j, n}$ for the $i$ th row, $i$ th column and typical element of [ $A_{n}, X_{n}$ ] respectively.

Assumption 11. $X_{n}$ is independent of $u_{i}, i=1, \ldots, n$,
$\max _{1 \leq i \leq n, p_{n}<j \leq p_{n}+k_{n}} \mathbb{E} t_{i j, n}^{2}<\infty$ and $\max _{1 \leq i \leq n, 1 \leq j \leq p_{n}} \mathbb{E} t_{i j, n}^{2}<C k_{n}^{2}$.
The independence of the entire regressor matrix $X_{n}$ from $u_{i}$ is needed due to each element of $A_{n}$ containing elements from different rows of $X_{n}$. The assumption implies that $\mathbb{E}\left\|t_{i n}\right\|^{2}=$ $\mathscr{O}\left(k_{n}+p_{n} k_{n}^{2}\right)$ and $\mathbb{E}\left\|m_{i n}\right\|^{2}=\mathscr{O}\left(n k_{n}^{2}\right)$, uniformly in $i$. The second part imposes finite second moments on elements of $X_{n}$. A sufficient condition for the last part is $\mathbb{E}\left\|X_{n}\right\|_{R}^{2}<C k_{n}^{2}$. This part restricts the expectation of the squared elements of $A_{n}$, motivated by the fact that the elements of $A_{n}$ are $\mathscr{O}\left(k_{n}\right)$ if $X_{n}$ is taken to consist of nonstochastic, uniformly bounded constants.
Assumption 12. As $n \rightarrow \infty,\left\{\underline{\eta}\left(\bar{L}_{n}\right)\right\}^{-1}=\mathscr{O}_{p}(1)$.
Theorem 4.1. Let Assumptions $1-4,8,11,12$ hold, and
$\frac{1}{p_{n}}+\frac{1}{k_{n}}+\frac{p_{n} k_{n}^{2}\left(p_{n}+k_{n}\right)}{n}+\frac{p_{n}}{h_{n}} \rightarrow 0 \quad$ as $n \rightarrow \infty$.
Then
$\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\| \xrightarrow{p} 0, \quad$ as $n \rightarrow \infty$.
Lee (2002) demonstrated consistency of OLS estimates for the model (1.1), for $p=1$, when $h_{n} \rightarrow \infty$. This condition ensures that the endogeneity problem caused by the spatially lagged $y_{n}$ vanishes asymptotically. Our condition (4.2) is suitably strengthened to also account for the increasing $p_{n}$ and $k_{n}$. To obtain a central limit theorem, we additionally assume

Assumption 13. $\mathbb{E} u_{i}^{4}=\mu_{4} \leq C$ for $i=1, \ldots, n$.
This is slightly weaker than Lee's (2002) condition $\mathbb{E}\left|u_{i}\right|^{4+\epsilon} \leq C$ for some $\epsilon>0$, for both consistency and asymptotic normality. We now introduce the OLS residual-based estimate of $\sigma^{2}$, defined as
$\tilde{\sigma}_{(n)}^{2}=n^{-1}\left\|y_{n}-\left[R_{n}, X_{n}\right] \tilde{\theta}_{(n)}\right\|^{2}$.
Theorem 4.2. Let Assumptions 1-4, 8, 11-13 hold, and
$\frac{1}{p_{n}}+\frac{1}{k_{n}}+\frac{p_{n} k_{n}^{2}\left(p_{n}+k_{n}\right)}{n}+\frac{p_{n}}{h_{n}} \rightarrow 0 \quad$ as $n \rightarrow \infty$.
Then
$\tilde{\sigma}_{(n)}^{2} \xrightarrow{p} \sigma^{2}$ as $n \rightarrow \infty$.

Assumption 14. $n^{-1} \max _{1 \leq i \leq n}\left\|t_{i n}\right\|^{2} \xrightarrow{p} 0$ as $n \rightarrow \infty$.
This condition can be satisfied for uniformly bounded and constant $X_{n}$ elements if $p_{n} k_{n}^{2}=o(n)$, as discussed for Assumption 9.

Assumption 15. There exists a constant, symmetric matrix $L_{n}$ with $\underline{\lim }_{n \rightarrow \infty} \underline{\eta}\left(L_{n}\right)>0$ and $\overline{\lim }_{n \rightarrow \infty} \bar{\eta}\left(L_{n}\right)<\infty$, and such that $\max \left\{p_{n}^{\frac{1}{2}} k_{n}, n^{\frac{1}{2}} p_{n}^{\frac{1}{2}} h_{n}^{-1}\right\}\left\|\bar{L}_{n}-L_{n}\right\|=o_{p}(1)$, as $n \rightarrow \infty$.
A similar comment to that after Assumption 10 pertaining to the rate condition holds. Here (A.19) in Appendix A can be used as a guide rate, and it is straightforward to see that the resulting orders would be negligible under (4.5).

Theorem 4.3. Let Assumptions 1-4, 8, 11-15 hold, and
$\frac{1}{p_{n}}+\frac{1}{k_{n}}+\frac{p_{n}^{2} k_{n}^{4}\left(p_{n}+k_{n}\right)}{n}+n^{\frac{1}{2}} \frac{p_{n}^{\frac{1}{2}}}{h_{n}} \rightarrow 0 \quad$ as $n \rightarrow \infty$.
Then
$\frac{n^{\frac{1}{2}}}{\left(p_{n}+k_{n}\right)^{\frac{1}{2}}} \Psi_{n}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right) \xrightarrow{d} N\left(0, \Xi_{3}\right) \quad$ as $n \rightarrow \infty$,
where $\Xi_{3}=\sigma^{2} \lim _{n \rightarrow \infty}\left(p_{n}+k_{n}\right)^{-1} \Psi_{n} L_{n}^{-1} \Psi_{n}^{\prime}$, which may be estimated consistently using $\tilde{\sigma}_{(n)}^{2}\left(p_{n}+k_{n}\right)^{-1} \Psi_{n} \overline{\bar{L}}_{n}^{-1} \Psi_{n}^{\prime}$.

Corollary 4.1. Let Assumptions 1-4, 8, 11-15 and (4.5) hold. Then
$n^{\frac{1}{2}}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)_{l} \xrightarrow{d} N\left(0, \sigma^{2} \Omega_{3}^{l}\right), \quad$ as $n \rightarrow \infty$,
where $\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)_{l}$ denotes the first lelements of $\hat{\theta}_{(n)}-\theta_{(n)}$ while the limiting top-left $l \times l$ block of $L_{n}^{-1}$ is denoted $\Omega_{3}^{l}$, and the asymptotic covariance matrix is estimated as in Theorem 4.3.

## 5. Illustrations

### 5.1. Panel data SAR models with fixed effects

Consider a balanced spatial panel data set with $N$ observations in each of $T$ individual panels, so that $n=N T$. Let $y_{t, N}$ be the $N \times 1$ vector of observations on the dependent variable for the $t$ th panel, where $t$ may correspond to a time period or a more general spatial unit like a school, village or district. Also let $X_{t N}$ and $F_{N}$ be $N \times k_{1}$ and $N \times k_{2}$ matrices of regressors respectively. $X_{t N}$ contains panelvarying regressors while $F_{N}$ does not. Consider the model

$$
\begin{align*}
y_{t N} & =l_{N} \alpha_{t}+X_{t N} \beta+F_{N} \zeta_{t}+\sum_{i=1}^{p} \lambda_{i} W_{i N} y_{t, N}+U_{t N} \\
t & =1, \ldots, T \tag{5.1}
\end{align*}
$$

where $U_{t N}$ is the $N \times 1$ vector of disturbances for each panel, formed of iid components. The $\alpha_{t}, t=1, \ldots, T$, are scalar fixed effect parameters, the $\lambda_{i}, i=1, \ldots, p$, are scalar and $\beta$ is a $k_{1} \times 1$ panel-invariant parameter vector, whereas $\zeta_{t}$ is a $k_{2} \times 1$ parameter vector that can vary with $t$. For this reason, $F_{N}$ may be thought of as controlling for 'quasi' fixed-effects. Denote $y_{n}=\left(y_{1 n}^{\prime}, \ldots, y_{T n}^{\prime}\right)^{\prime}$, $X_{n}=\left(X_{1 n}^{\prime}, \ldots, X_{T n}^{\prime}\right)^{\prime}, U_{n}=\left(U_{1 n}^{\prime}, \ldots, U_{T n}^{\prime}\right)^{\prime}, \alpha=\left(\alpha_{1}, \ldots, \alpha_{T}\right)^{\prime}$ and $\zeta=\left(\zeta_{1}, \ldots, \zeta_{T}\right)^{\prime}$. We can then stack (5.1) to obtain

$$
\begin{align*}
y_{n}= & \left(I_{T} \otimes l_{N}\right) \alpha+X_{n} \beta+\left(I_{T} \otimes F_{N}\right) \zeta \\
& +\sum_{i=1}^{p} \lambda_{i}\left(I_{T} \otimes W_{i N}\right) y_{n}+U_{n} \tag{5.2}
\end{align*}
$$

This model extends that of Kelejian et al. (2006), and was employed by Yuzefovich (2003). As $n \rightarrow \infty, N \rightarrow \infty$ and/or $T \rightarrow \infty$, and the dimension of $\zeta$ can diverge. Also, since the $I_{T} \otimes W_{i N}$ are block diagonal it would be natural to fear that spatial autoregressive parameters differ across panels, or at least among subsets of the panels. For example, allowing a separate spatial parameter for each panel when $p=1$ implies the model
$y_{n}=\left(I_{T} \otimes l_{N}\right) \alpha+X_{n} \beta+\left(I_{T} \otimes F_{N}\right) \zeta+\sum_{i=1}^{T} \lambda_{i} W_{N}^{(i)} y_{n}+U_{n}$
where $W_{N}^{(i)}$ has a single nonzero diagonal block structure with $V_{\text {in }}=W_{N}$, say, $i=1, \ldots, T$. (5.3) has $k_{1}+T\left(k_{2}+1\right)$ regression parameters and $T$ spatial parameters, making it fit naturally into the asymptotic regime discussed in Sections 3 and 4. In this context condition $p_{n}^{3} k_{n}^{4}=o(n)$ (a sufficient condition for asymptotic normality of OLS in Section 4) translates to $T^{6} / N \rightarrow 0$ as $N, T \rightarrow \infty$.

### 5.2. Models with circulant weight matrices

Define $W_{i n}^{*}$ as the symmetric circulant matrix with first row elements given by
$w_{1 j, \text { in }}^{*}= \begin{cases}0 & \text { if } j=1 \text { or } j=i+2, \ldots, n-i ; \\ 1 & \text { if } j=2, \ldots, i+1 \text { or } j=n-i+1, \ldots, n .\end{cases}$
Thus the weight matrix $W_{i n}^{*}$ encapsulates a binary neighbourhood criterion for $i$ neighbours on either 'side' of a unit (see Das et al. (2003)). For instance, with $n=4$
$W_{1 n}^{*}=\left[\begin{array}{llll}0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0\end{array}\right]$.
Now define
$W_{i n}=\left\|W_{i n}^{*}\right\|^{-1} W_{i n}^{*}$,
where $\left\|W_{i n}^{*}\right\|=\bar{\eta}\left(W_{i n}^{*}\right)=2 i$ because $W_{i n}^{*}$ is a symmetric, circulant matrix (see e.g. Davis (1979) p. 73), implying that (5.5) is rownormalization. Then $W_{i n}$ is also a symmetric circulant matrix with first row elements given by $w_{1 j, \text { in }}^{*} / 2 i$.

The maximum number of neighbours is determined by $n$. We must have $p_{n}<\lceil n / 2\rceil$ where $\lceil a\rceil$ denotes the smallest integer greater than or equal to $a$. The $W_{i n}$ are easily seen to be linearly independent by showing linear independence of the first rows. Indeed take any finite set $\left\{W_{i n}: i=1, \ldots, s\right\}$, and suppose that $\sum_{i=1}^{s} \xi_{i} w_{1, \text { in }}^{\prime}=0$, where $w_{1, i n}^{\prime}$ denotes the first row of $W_{i n}$ and $\xi_{i}$ are scalars. It immediately follows that $\xi_{s}=0$, implying $\sum_{i=1}^{s-1} \xi_{i} w_{1, \text { in }}^{\prime}=0$ so $\xi_{s-1}=0$. We conclude that $\xi_{i}=0$ for each $i=1, \ldots$, .

Note that OLS cannot be used to estimate (2.1) with these $W_{i n}$, because as the number of neighbours increases with $n$ this is reflected in additional weight matrices. It is possible to obtain consistent and asymptotically normal IV estimates, however.

## 6. Empirical example

In this section we provide a small empirical illustration of how a richer model may provide more insight into economic problems. Kolympiris et al. (2011) (henceforth KKM) attempt to explain the level of venture capital funding (provided by venture capital firms (VCFs)) for dedicated biotechnology firms (DBFs) with a SAR model. In particular, the hypotheses are that the level of VC funding for a DBF increases with the number of VCFs located in close proximity to the DBF and with the number of other

DBFs located in close proximity to the DBF. To model this (1.1) is employed. Denoting by $d_{l k}$ the distance in miles between the lth and $k$ th DBFs, they estimated
$y_{n}=\sum_{i=1}^{3} \lambda_{i} W_{i n}^{b} y_{n}+X_{n} \beta+U_{n}$,
where $W_{i n}^{b}$ is the row-normalized version of a weight matrix having off-diagonal $(l, k)$ th element equal to 1 if $10(i-1)<d_{l k} \leq 10 i$, $i=1,2,3$, and if $d_{l k}=0$ for $i=1$. Thus each weight matrix is based on one of 3 sequential 10 -mile rings from the origin DBF. Because the number of neighbours may be taken to increase with sample size, OLS was used. $y_{n}$ is taken to comprise the natural logs of the amount of VC funding (million \$) received by each of $n=816$ DBFs. The authors include several explanatory variables in $X_{n}$, described below. The number of VCFs within 10 miles of the origin DBF (VC010), between 10.01 and 20 miles (VC1020), between 20.01 and 30 miles (VC2030), similarly the number of DBFs within three 10 -mile rings of the origin DBF (DBF010, DBF1020, DBF2030) capture the effects of being in areas of high VCF or DBF concentration. There are also firm-specific factors for the VCFs. These include a variable that measures the natural logarithm of the average (weighted by funding share) distance from each DBF to the VCFs that fund it (VCDist), the average total amount invested in all firms by each VCF that funded the origin DBF (VCSize), the average age of each VCF (as of 2007) that funded the origin DBF (VCAge), the average number of other DBFs a funding VCF of the origin DBF co-invested in through syndication (VCSynd), a dummy variable (Foreign) that equals 1 if the origin DBF received funds from non-US VCFs (and equals 0 otherwise). Variables controlling for DBF-specific factors include the age of a DBF (Age, Age ${ }^{2}$ ) to capture concavity in the sense that a mature firm will rely less on VCF, yet also be more attractive to VCFs. The dummy variable SBIR equals one if the DBF received Small Business Innovation Research (SBIR) grants (and equals 0 otherwise), while another dummy variable (Tax) equals one if the DBF's state had an R\&D tax credit from 1990 to 2007. Also included are an index of the cost of doing business in the DBF's state (Business), the distance from a DBF to the closest university (University) and the average total number of non-biotech establishments (Establishments) in the DBF's zip code from 1990 to 2007. The final two variables recognize that additional factors can affect the cost of doing business in ways that influence the VC funding levels of a given DBF. The first is defined as Cross $=W_{N S} \times D$, where $W_{N S}$ is a $n \times n$ nonstandardized spatial weight matrix that identifies the firms located within a 1 -mile radius from the origin firm, and $D$ is the $n \times 1$ vector of the weighted distance for each firm from its financing VCFs. Cross increases in both the number of firms within 1-mile and in distance from funding VCFs, so it captures the potential increase of VC funds realized by firms closely surrounded by a large number of firms funded by distant VCFs. The second (LocalVC) measures the number of DBFs located less than 10 miles from the origin DBF which were funded by $\operatorname{VCF}(s)$ located in the same radius that also funded the origin DBF , accounting for potential cost efficiencies realized by VCFs when they invest in proximate firms. An intercept is also included. We omit a more detailed discussion of the variables to conserve space, but this is available in KKM.

KKM discover that only the spatial lag corresponding to the first 10 mile ring is significant. Of the regressors in $X_{n}$, only the following were found to be significant at the 5\% level: Age, $\mathrm{Ag}^{2}$, SBIR, VCFSynd, Foreign, LocalVC, VCDist and DBF010, apart from the intercept. We extend the analysis by reducing the radius of the rings used in defining neighbours to 1 mile, in keeping with our suggestion that with a fairly large sample of 816 observations a richer model can be estimated. The specification is
$y_{n}=\sum_{i=1}^{10} \lambda_{i} W_{i n}^{b} y_{n}+X_{n} \beta+U_{n}$,

Table 6.1
OLS estimates of $\lambda_{i}$ in (6.2) and (6.3).

| Parameter | Specification | $(6.3)$ |
| :--- | :--- | :--- |
|  | $(6.2)$ | $0.1051^{*}$ |
| $\lambda_{1}$ | $0.0964^{*}$ | $(4.6698)$ |
|  | $(2.7428)$ |  |
| $\lambda_{2}$ | $0.0823^{*}$ |  |
| $\lambda_{3}$ | $(2.1982)$ |  |
|  | -0.0058 | $(0.1482)$ |
| $\lambda_{4}$ | 0.0594 |  |
|  | $(1.5344)$ |  |
| $\lambda_{5}$ | 0.0046 | $(0.1299)$ |
| $\lambda_{6}$ | 0.0128 | $(0.3753)$ |
| $\lambda_{7}$ | 0.0261 |  |
| $\lambda_{8}$ | $(0.8168)$ |  |
|  | 0.0265 | $(0.7951)$ |
| $\lambda_{9}$ | 0.0560 | $(1.5007)$ |
| $\lambda_{10}$ | 0.0408 |  |
|  | $(1.1477)$ |  |

In parentheses are absolute $t$-ratios (based on heteroskedasticity-consistent standard errors).
${ }^{*} 5 \%$ significance.
where now $W_{i n}^{b}$ is the row-normalized version of a weight matrix having off-diagonal ( $l, k$ )th element equal to 1 if $i-1<d_{l k} \leq i$, $i=1 \ldots, 10$, and if $d_{l k}=0$ for $i=1$.

The first columns on the right of Tables 6.1 and 6.2 report the autoregressive and regression coefficient estimates, respectively, from (6.2). Only the first two spatial lags are significant at the $5 \%$ level, implying that spatial dependence is restricted to a small geographical radius. A test of $\lambda_{1}=\lambda_{2}$ returned a $t$-statistic of 0.2609 , not ruling out equal spatial dependence from each ring. The regression coefficient estimates broadly correspond in sign and magnitude to those in KKM, with three exceptions. Allowing for 'thinner' rings increases the significance of DBF010, DBF2030 and VC010. The first was found to be significant at the $10 \%$ level by KKM but is now significant at even $0.1 \%$, while the latter two were insignificant but are now significant at the $5 \%$ level. The impact on VC funding of having competing DBFs in the geographical area may operate in two opposite directions. On the one hand areas of high DBF concentration may attract more VC funding for all firms, while on the other the competition for VC funds may have a negative impact. It is evident that allowing for a richer model has enabled us to pick up the non-negligible latter impact. Similarly a concentration of VCFs in close vicinity has a positive impact on DBF funding. In light of the analysis above we also estimate
$y_{n}=\lambda_{1}\left(W_{1 n}^{b}+W_{2 n}^{b}\right) y_{n}+X_{n} \beta+U_{n}$.
The results are reported in the second columns on the right of Tables 6.1 and 6.2. There are no major changes in the conclusions qualitatively. DBF010 remains significant but DBF2030 no longer does, while VC 1020 also becomes significant. The intercept loses significance marginally.

## 7. Monte Carlo experiments

Two sets of Monte Carlo experiments were carried out with three aims. First, to assess the extent to which more data improve precision of estimates despite increasing number of parameters, and to understand the rate at which this may happen. Second, to check the relative performance of the OLS and IV estimates for various values of $p_{n}^{2} / n$. Third, to examine the rate of change of the precision of estimates as the ratio $p_{n}^{2} / n$ changes.

Table 6.2
OLS estimates of (6.2) and (6.3): regression coefficients.

| Variables | Specification |  |
| :---: | :---: | :---: |
|  | (6.2) | (6.3) |
| Intercept | $\begin{aligned} & -1.4542^{*} \\ & (2.1906) \end{aligned}$ | $\begin{array}{r} -1.1678 \\ (1.9235) \end{array}$ |
| Age (years) | $\begin{aligned} & 0.2499 \\ & (5.1138) \end{aligned}$ | $\begin{aligned} & 0.2520 \\ & (5.1236) \end{aligned}$ |
| $\mathrm{Age}^{2}$ (years) | $\begin{aligned} & -0.0120^{*} \\ & (4.3680) \end{aligned}$ | $\begin{aligned} & -0.0120^{\prime} \\ & (4.3631) \end{aligned}$ |
| SBIR (binary) | $\begin{aligned} & 0.2368 \\ & (2.3253) \end{aligned}$ | $\begin{aligned} & 0.2120 \\ & (2.0637) \end{aligned}$ |
| Tax (binary) | $\begin{aligned} & -0.1503 \\ & (0.6215) \end{aligned}$ | $\begin{aligned} & -0.0674 \\ & (0.2861) \end{aligned}$ |
| VCDist (miles) | $\begin{aligned} & -0.0020 \\ & (0.6485) \end{aligned}$ | $\begin{aligned} & -0.0028 \\ & (0.9147) \end{aligned}$ |
| Business | $\begin{aligned} & 0.0034 \\ & (0.5681) \end{aligned}$ | $\begin{aligned} & 0.0003 \\ & (0.0721) \end{aligned}$ |
| Establishments | $\begin{aligned} & 0.0174 \\ & (0.2938) \end{aligned}$ | $\begin{aligned} & 0.0315 \\ & (0.5469) \end{aligned}$ |
| VCSize | $\begin{aligned} & 0.0000 \\ & (0.9062) \end{aligned}$ | $\begin{aligned} & 0.0000 \\ & (0.9063) \end{aligned}$ |
| VCAge | $\begin{aligned} & 0.0049 \\ & (0.7880) \end{aligned}$ | $\begin{aligned} & 0.0037 \\ & (0.6048) \end{aligned}$ |
| VCSynd level | $\begin{aligned} & 0.0336 \\ & (5.4671) \end{aligned}$ | $\begin{aligned} & 0.0350 \\ & (5.7465) \end{aligned}$ |
| Foreign (binary) | $\begin{aligned} & 1.1754 \\ & (12.6853) \end{aligned}$ | $\begin{aligned} & 1.1819 \\ & (12.8610) \end{aligned}$ |
| VCDist | $\begin{aligned} & 0.2172 \\ & (5.8581) \end{aligned}$ | $\begin{aligned} & 0.2214 \\ & (6.0478) \end{aligned}$ |
| Cross | $\begin{aligned} & 0.0012 \\ & (1.2103) \end{aligned}$ | $\begin{aligned} & 0.0000 \\ & (0.0618) \end{aligned}$ |
| LocalVC | $\begin{aligned} & 0.0229 \\ & (3.3887) \end{aligned}$ | $\begin{aligned} & 0.0226 \\ & (3.3145) \end{aligned}$ |
| DBF010 | $\begin{aligned} & -0.0057 \\ & (2.9790) \end{aligned}$ | $\begin{aligned} & -0.0032 \\ & (2.0458) \end{aligned}$ |
| DBF1020 | $\begin{aligned} & -0.0022 \\ & (0.8710) \end{aligned}$ | $\begin{aligned} & -0.0016 \\ & (0.6400) \end{aligned}$ |
| DBF2030 | $\begin{aligned} & -0.0061 \\ & (2.0223) \end{aligned}$ | $\begin{aligned} & -0.0052 \\ & (1.8100) \end{aligned}$ |
| VCF010 | $\begin{aligned} & 0.0049 \\ & (2.1070) \end{aligned}$ | $\begin{aligned} & 0.0071 \\ & (3.2732) \end{aligned}$ |
| VCF1020 | $\begin{aligned} & 0.0052 \\ & (1.5818) \end{aligned}$ | $\begin{aligned} & 0.0065 \\ & (2.0636) \end{aligned}$ |
| VCF2030 | $\begin{aligned} & 0.0048 \\ & (1.5528) \end{aligned}$ | $\begin{aligned} & 0.0043 \\ & (1.4227) \end{aligned}$ |

In parentheses are absolute $t$-ratios (based on heteroskedasticity-consistent standard errors).

* $5 \%$ significance.

In the first set of experiments we chose weight matrices as (1.3) and (1.4). The number of regressors was kept fixed at $k_{n}=2$ for simplicity, and we experimented with $p=2,6,18$ and $m=$ $50,150,450$. Note that in this setting we have $p_{n}=p$ and $n=p m$ so that $p_{n}^{2} / n=p / m$. The elements of $X_{n}$ were generated from a uniform distribution on ( 0,1 ), and kept fixed over replications. The $u_{i}$ were generated as iid draws from a standard normal ( $\sigma^{2}=1$ ) distribution, and instruments were constructed as in (3.3) using only first-order spatial lags of the regressors $(j=1)$. The vector $y_{n}$ was generated using (1.1) and (1.4) (without $H_{n}$ ) in each of the 1000 replications. We chose $\beta_{1}=1, \beta_{2}=0.5$ and $\lambda_{1}=0.7, \lambda_{2}=0.8$, $\lambda_{3}=0.5, \lambda_{4}=0.8, \lambda_{5}=0.3, \lambda_{6}=0.6, \lambda_{7}=0.7, \lambda_{8}=0.8$, $\lambda_{9}=0.5, \lambda_{10}=0.8, \lambda_{11}=0.3, \lambda_{12}=0.6, \lambda_{13}=0.7, \lambda_{14}=0.8$, $\lambda_{15}=0.5, \lambda_{16}=0.8, \lambda_{17}=0.3, \lambda_{18}=0.6$. For our analysis we employ Monte Carlo average mean-squared error (AMSE) defined as $\operatorname{AMSE}\left(\hat{\theta}_{(n)}\right)=s^{-1} \sum_{i=1}^{s} \operatorname{MSE}\left(\hat{\theta}_{\text {in }}\right)$, with $\operatorname{MSE}\left(\hat{\theta}_{i n}\right)$ denoting the Monte Carlo MSE for the IV estimate of the $i$ th element $\hat{\theta}_{\text {in }}$ in the $s \times 1$ vector $\hat{\theta}_{(n)} . \operatorname{AMSE}\left(\tilde{\theta}_{(n)}\right)$ is defined analogously.

Define the relative AMSE (RAMSE) as $\operatorname{RAMSE}\left(Q_{1}, Q_{2}\right)=$ $\operatorname{AMSE}\left(Q_{1}\right) / \operatorname{AMSE}\left(Q_{2}\right)$, for two generic estimators $Q_{1}$ and $Q_{2}$. Table 7.1 presents AMSE and RAMSE of the IV and OLS estimates for various combinations of $p$ and $m$. The AMSE for both reduces


Fig. 7.1. Monte Carlo log RAMSE for IV estimates $\hat{\theta}_{(n)}$.
for fixed $p$ and increasing $m$. Interestingly this happens also for fixed $m$ and increasing $p$, indicating that the claim of being able to precisely estimate increasingly many parameters is reasonable. The RAMSE indicates that even though OLS is asymptotically efficient IV outperforms it in many cases. Additional simulations (not reported here) indicate that OLS tends to perform better for larger values of $m$. For instance, when $p=2$ and $m=3000$ the RAMSE is 1.0301 . Recall that in this setting $h_{n}=m-1$, supporting the theory that $h_{n} \rightarrow \infty$ is required for consistency of OLS with a fast rate of divergence required for asymptotic normality, while the properties of IV do not depend on the divergence of $h_{n}$.

Figs. 7.1(a)-(c) and 7.2(a)-(c) plot the log RAMSE (LRAMSE) for $\hat{\theta}_{(n)}$ and $\tilde{\theta}_{(n)}$ for all possible ratios $p / m$. Fig. 7.1(a) illustrates LRAMSE for the IV estimate $\hat{\theta}_{(n)}$ when $p=2$. The points on the horizontal axis correspond to all choices of $p / m$ and the vertical axis measures LRAMSE. Each solid dot on the figure marks out the LRAMSE of $\hat{\theta}_{(n)}$ for a particular value of $m$ relative to that of $\hat{\theta}_{(n)}$ for the corresponding ratio on the horizontal axis. The solid line joins the LRAMSE for $m=50$, the heavy dotted line for $m=150$ and the light dotted line for $m=450$. Fig. 7.1(b), (c) repeats the analysis for $p=6$ and $p=18$ respectively, again the solid lines joining the LRAMSE for $m=50$, the heavy dotted lines for $m=150$ and the light dotted lines for $m=450$. Fig. 7.2(a)-(c) does exactly the same for the OLS estimate $\tilde{\theta}_{(n)}$. By definition the LRAMSE of an estimate with itself corresponds to a value of zero. Negative LRAMSE values indicate that the estimate for which a line is plotted outperforms the comparator indicated on the horizontal axis, while the opposite holds true for positive values. For ease of interpretation a thin solid horizontal line is passed through zero.

Table 7.1
Monte Carlo AMSE and RAMSE of IV and OLS estimates using (1.4).

| $p$ | $m$ | 50 | 150 | 450 |
| :--- | :--- | :--- | :--- | :--- |
| 2 | $\operatorname{AMSE}\left(\hat{\theta}_{(n)}\right)$ | 0.0693 | 0.0219 | 0.0076 |
|  | $\operatorname{AMSE}\left(\tilde{\theta}_{(n)}\right)$ | 0.0714 | 0.0232 | 0.0076 |
|  | $\operatorname{RAMSE}\left(\hat{\theta}_{(n)}, \tilde{\theta}_{(n)}\right)$ | 0.9706 | 0.9450 | 1.0000 |
| 6 | $\operatorname{AMSE}\left(\hat{\theta}_{(n)}\right)$ | 0.0243 | 0.0071 | 0.0022 |
|  | $\operatorname{AMSE}\left(\tilde{\theta}_{(n)}\right)$ | 0.0283 | 0.0074 | 0.0023 |
|  | $\operatorname{RAMSE}\left(\hat{\theta}_{(n)}, \tilde{\theta}_{(n)}\right)$ | 0.8594 | 0.9599 | 0.9663 |
|  | $\operatorname{AMSE}\left(\hat{\theta}_{(n)}\right)$ | 0.0115 | 0.0033 | 0.0010 |
|  | $\operatorname{AMSE}\left(\tilde{\theta}_{(n)}\right)$ | 0.0184 | 0.0038 | 0.0011 |
|  | $\operatorname{RAMSE}\left(\hat{\theta}_{(n)}, \tilde{\theta}_{(n)}\right)$ | 0.6250 | 0.8479 | 0.9218 |

We now analyse Fig. 7.1(a) in detail. The solid line increases through LRAMSE comparisons for estimates with $p=2$ but higher values of $m$. While the value of LRAMSE then dips for $p=6$ and $m=50$, it is still positive. This indicates that 8 parameters are more accurately estimated with 300 observations as opposed to 4 parameters with 100 observations. The LRAMSE then increases in the $p=6$ range, before dropping and then increasing again in the $p=18$ range. We make two comments about these results, reflective of the discussion of Table 7.1. First, estimates become more precise for given $p$ with increasing $m$. Second, many more


Fig. 7.2. Monte Carlo log RAMSE for OLS estimates $\tilde{\theta}_{(n)}$.

Table 7.2
Monte Carlo AMSE of IV estimates using (5.5).

| $p$ | $n$ | 108 | 432 | 864 |
| :--- | :--- | :--- | :--- | :--- |
| 2 | AMSE $\left(\hat{\theta}_{(n)}\right)$ | 0.3981 | 0.0810 | 0.0350 |
| 4 | AMSE $\left(\hat{\theta}_{(n)}\right)$ | 2.4391 | 0.5684 | 0.2355 |

parameters can be estimated much more accurately with increasing data. The first point suggests that in practice, when a data set of a given size is available, researchers should try to reduce the number of parameters to obtain more precise estimates. This may be achieved in a variety of ways in SAR models, as discussed earlier. The heavy dotted $(m=150)$ and light dotted $(m=450)$ lines behave in the same way, the difference being that the initial values of LRAMSE are negative. This is because, for instance, the first point on the heavy dotted line corresponds to the LRAMSE of the
estimate with $p=2$ and $m=150$ to the estimate with $p=2$ and $m=50$. This is simply the log of the reciprocal of the value whose $\log$ is the second point on the solid line. Analysis of the other figures indicates the same pattern in the rate of change of the LRAMSE.

The second set of experiments employed the weight matrices (5.5). We considered $p=2,4, n=108,432,864$ and chose $\lambda_{1}=0.2, \lambda_{2}=0.1, \lambda_{3}=0.2, \lambda_{4}=0.1$ to satisfy (3.2). The remainder of the design was kept identical to that considered in the first set of experiments. In this setting only IV estimates were considered (cf. Section 5), with instruments given again by firstorder spatial lags of $X_{n}$. Table 7.2 presents the results. The AMSE is seen to decline with increasing $n$ but remain rather high for $p=4$ even when $n=864$. The choice of lag order should be economically motivated but seems to depend heavily on $n$, with rather large $n$ needed to justify even moderate choices of $p$.

Table 7.3 displays average Monte Carlo sizes of tests based on IV and OLS and Theorems 3.3 and 4.3, for various combinations of $p$ and $n$, and using both specifications for weight matrices. These

Table 7.3
Monte Carlo average sizes.

| $p$ | $m$ | Using (1.4) |  |  | $p$ | $n$ | Using (5.5) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 50 | 150 | 450 |  |  | 108 | 432 | 864 |
| 2 | $\hat{\theta}_{(n)}$ | 0.0590 | 0.0473 | 0.0520 | 2 | $\hat{\theta}_{(n)}$ | 0.0305 | 0.0403 | 0.0498 |
|  | $\tilde{\theta}_{(n)}$ | 0.0612 | 0.0443 | 0.0460 |  |  |  |  |  |
| 6 | $\hat{\theta}_{(n)}$ | 0.0464 | $0.0484$ | $0.0452$ | 4 | $\hat{\theta}_{(n)}$ | 0.0172 | 0.0428 | 0.0535 |
|  | $\tilde{\theta}_{(n)}$ | 0.0623 | 0.0530 | 0.0507 |  |  |  |  |  |
| 18 | $\hat{\theta}_{(n)}$ | $0.0488$ | 0.0493 | $0.0511$ |  |  |  |  |  |
|  | $\tilde{\theta}_{(n)}$ | 0.0771 | 0.0560 | 0.0542 |  |  |  |  |  |

sizes should be compared with the nominal $5 \%$. The table indicates that the sizes approach the nominal value as $n$ increases, though not always monotonically. When using (5.5) there tends to be mostly undersizing, quite severe for smaller $n$ owing to the issues discussed above. On the other hand, when using (1.4) OLS usually oversizes while IV usually undersizes, but neither does so greatly. On the whole, the asymptotic distributions seem to provide a reasonable approximation.

## 8. Conclusion

Asymptotic theory has been presented for a general class of spatial autoregressive models with increasingly many parameters, and with at least one non-intercept regressor. The theory is thus not applicable to the pure SAR model or the SAR model with only an intercept regressor, though analogous theory for this can be developed using parameter estimates such as the Gaussian pseudo maximum likelihood estimate (PMLE). The latter (studied by Lee (2004) in the $p=1$ case) provides consistent and efficient estimates under weaker conditions on $h_{n}$ than OLS and also, unlike OLS and IV, can estimate models with no explanatory variables, or only an intercept. It may be worth investigating data-dependent choices of $p$, though in the SAR context a higher order does not necessarily reflect greater distance.

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## Appendix A. Proofs of results in Sections 2-4

Write $a_{n}=p_{n}+s_{n}+k_{n}, b_{n}=r_{n}+k_{n}, c_{n}=p_{n} k_{n}^{2}+k_{n}$ and $\tau_{n}=n^{\frac{1}{2}} / a_{n}^{\frac{1}{2}}$. For any matrices $F_{n}, \bar{F}_{n}$ and $\overline{\bar{F}}_{n}$ of equal dimension, we will write $\overline{\bar{\Delta}}_{n}^{F}=\bar{F}_{n}-\overline{\bar{F}}_{n}, \bar{\Delta}_{n}^{F}=F_{n}-\bar{F}_{n}$.

Proof of Proposition 2.1. By definition, $S_{n}=I_{n}-\operatorname{diag}\left[\lambda_{1 n} V_{1 n}\right.$, $\ldots, \lambda_{p_{n} n} V_{p_{n}}$ ], with unit diagonal elements. With $v_{l k, i n}$ denoting a typical element of $V_{i n}$, due to row-normalization we have $\sum_{s \neq r, m \neq l}\left|\lambda_{i n}\right|^{2}\left|v_{r s, i n}\right|\left|v_{l m, i n}\right|<1$ if $\lambda_{i n}^{2}<1$, whence the claim follows from Horn and Johnson (1985), p. 381, Corollary 6.4.11 (b).

Proof of Lemma 3.1. (i) For any $a_{n} \times 1$ vector $x_{n}$ satisfying $\left\|x_{n}\right\|=$ 1, $x_{n}^{\prime} \bar{K}_{n}^{\prime} \bar{J}_{n}^{-1} \bar{K}_{n} x_{n} \geq \underline{\eta}\left(\bar{K}_{n}^{\prime} \bar{K}_{n}\right) / \bar{\eta}\left(\bar{J}_{n}\right)$, whence the lemma follows by Assumption 6. The proof of (ii) is similar.

Proof of Theorem 3.1. Write

$$
\begin{align*}
\hat{\theta}_{(n)}-\theta_{(n)}= & \bar{Q}_{n}^{-1} \overline{\bar{U}}_{n}^{Q}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right) \\
& -\bar{Q}_{n}^{-1} \overline{\bar{U}}_{n}^{K^{\prime}} \bar{J}_{n}^{-1} q_{n}+\bar{Q}_{n}^{-1} \bar{K}_{n}^{\prime} J_{n}^{-1} q_{n} . \tag{A.1}
\end{align*}
$$

By elementary norm inequalities $\left\|\overline{\bar{\Delta}}_{n}^{Q}\right\| \leq\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|\left\|\bar{J}_{n}^{-1}\right\|\left(\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|+\right.$ $\left.2\left\|\bar{K}_{n}\right\|\right)$, where $\mathbb{E}\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|^{2}$ is bounded by $\sigma^{2} \sum_{i=1}^{b_{n}} \mathbb{E}\left\|p_{i n}\right\|^{2} \sum_{j=1}^{p_{n}}$ $\left\|G_{j n}\right\|^{2} / n^{2}=\mathscr{O}\left(p_{n} b_{n} / n\right)$, by Assumption 5 and Lemma B.1. We conclude that
$\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|=\mathscr{O}_{p}\left(n^{-\frac{1}{2}} p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}}\right)$,
by Markov's inequality. Then

$$
\begin{align*}
\left\|\overline{\bar{\Delta}}_{n}^{Q}\right\| & =\mathscr{O}_{p}\left(\max \left\{n^{-1} p_{n} b_{n}, n^{-\frac{1}{2}} p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}}\right\}\right) \\
& =\mathscr{O}_{p}\left(n^{-\frac{1}{2}} p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}}\right) \tag{A.3}
\end{align*}
$$

by Assumption 7. Likewise $\mathbb{E}\left\|q_{n}\right\|^{2}=\sigma^{2} \sum_{i=1}^{n} \mathbb{E}\left\|a_{i n}\right\|^{2} / n^{2}=$ $\mathscr{O}\left(b_{n} / n\right)$, by Assumption 5. By Markov's inequality

$$
\begin{equation*}
\left\|q_{n}\right\|=\mathscr{O}_{p}\left(n^{-\frac{1}{2}} b_{n}^{\frac{1}{2}}\right) . \tag{A.4}
\end{equation*}
$$

From (A.1),

$$
\begin{align*}
& \left(1-\left\|Q_{n}^{-1}\right\|\left\|\overline{\bar{\Delta}}_{n}^{Q}\right\|\right)\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\| \\
& \leq\left\|\bar{Q}_{n}^{-1}\right\|\left\|\bar{J}_{n}^{-1}\right\|\left\|q_{n}\right\|\left(\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|+\left\|\bar{K}_{n}\right\|\right) . \tag{A.5}
\end{align*}
$$

By (A.3) the first factor on the LHS converges in probability to one by (3.5) and Lemma 3.1(i), the first two factors on the RHS of (A.5) are $\mathscr{O}_{p}(1)$ by Assumption 7. The third and fourth factors have orders given in (A.2) and (A.4) respectively, implying that

$$
\begin{align*}
\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\| & =\mathscr{O}_{p}\left(\max \left\{n^{-1} p_{n}^{\frac{1}{2}} b_{n}, n^{-\frac{1}{2}} b_{n}^{\frac{1}{2}}\right\}\right) \\
& =\mathscr{O}_{p}\left(n^{-\frac{1}{2}} b_{n}^{\frac{1}{2}}\right) \tag{A.6}
\end{align*}
$$

This is negligible by (3.5). The proof of Corollary 3.2 is similar.
Proof of Theorem 3.2. Write

$$
\begin{aligned}
\hat{\sigma}_{(n)}^{2}= & n^{-1} U_{n}^{\prime} U_{n}-2\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)^{\prime} w_{n} \\
& +\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)^{\prime} \overline{\bar{L}}_{n}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right) .
\end{aligned}
$$

From Assumption 1, $n^{-1} U_{n}^{\prime} U_{n}=\sigma^{2}+o_{p}(1)$. Also by (A.6) and (A.17) the modulus of the second term is bounded by $\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\|$ $\left\|w_{n}\right\|=\mathscr{O}_{p}\left(\max \left\{b_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}} / n, p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}} / n^{\frac{1}{2}} h_{n}^{\frac{1}{2}}\right\}\right)$ while the third term has modulus bounded by

$$
\begin{aligned}
& \left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\|^{2}\left(\left\|\bar{L}_{n}\right\|+\left\|\overline{\bar{\Delta}}_{n}^{L}\right\|\right) \\
& \quad=\mathscr{O}_{p}\left(b_{n} \max \left\{n^{-1}, n^{-\frac{3}{2}} p_{n}^{\frac{1}{2}} k_{n} a_{n}^{\frac{1}{2}},\left(n h_{n}\right)^{-1} p_{n}\right\}\right)
\end{aligned}
$$

using (A.6), (A.19) and Assumption 8. Because $p_{n}^{\frac{1}{2}} k_{n} a_{n}^{\frac{1}{2}} b_{n} / n^{\frac{3}{2}}$ and $p_{n} b_{n} / n h_{n}$ are dominated by $b_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}} / n$ and $p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}} / n^{\frac{1}{2}} h_{n}^{\frac{1}{2}}$ respectively under (3.9), we have

$$
\begin{align*}
& \hat{\sigma}_{(n)}^{2}-\sigma^{2} \\
& \quad=\mathscr{O}_{p}\left(\max \left\{n^{-1} b_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}},\left(n^{\frac{1}{2}} h_{n}^{\frac{1}{2}}\right)^{-1} p_{n}^{\frac{1}{2}} b_{n}^{\frac{1}{2}}, n^{-1} b_{n}\right\}\right), \tag{A.7}
\end{align*}
$$

which is negligible by (3.9) and because $h_{n}$ is bounded away from zero.

Proof of Theorem 3.3. Let $\alpha$ be any non-null $q \times 1$ vector of constants and write

$$
\begin{align*}
\tau_{n} \alpha^{\prime} & \Psi_{n}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right) \\
= & \tau_{n} \alpha^{\prime} \Psi_{n} \bar{Q}_{n}^{-1} \overline{\bar{U}}_{n}^{Q}\left(\hat{\theta}_{(n)}-\theta_{(n)}\right)-\tau_{n} \alpha^{\prime} \Psi_{n}\left(\bar{Q}_{n}^{-1} \overline{\bar{\Delta}}_{n}^{K^{\prime}} \bar{J}_{n}^{-1}\right. \\
& -\bar{Q}_{n}^{-1} \bar{\Delta}_{n}^{Q} Q_{n}^{-1} \bar{K}_{n}^{\prime} \bar{J}_{n}^{-1}+Q_{n}^{-1} \bar{\Delta}_{n}^{K^{\prime}} J_{n}^{-1} \\
& \left.-Q_{n}^{-1} K_{n}^{\prime} \bar{J}_{n}^{-1} \bar{\Delta}_{n}^{J} J_{n}^{-1}\right) q_{n}+\tau_{n} \alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} q_{n} . \tag{A.8}
\end{align*}
$$

We first show that the first term on the RHS of (A.8) is $o_{p}(1)$. It has modulus bounded by $\tau_{n}\|\alpha\|\left\|\Psi_{n}\right\|\left\|\hat{\theta}_{(n)}-\theta_{(n)}\right\|\left\|Q_{n}^{-1}\right\|\left\|\overline{\bar{\Delta}}_{n}^{Q}\right\|=$ $\mathscr{O}_{p}\left(p_{n}^{\frac{1}{2}} b_{n} / n^{\frac{1}{2}}\right)$, by (A.3), (A.6) and Assumption 7, 10. This is negligible by (3.10) because $b_{n}^{2} \leq 2\left(r_{n}^{2}+k_{n}^{2}\right)$. Similarly (A.4), Assumption 6, 7, 10 and Lemma 3.1 imply that the second term on the RHS of (A.8) is $\mathscr{O}_{p}\left(b_{n}^{\frac{1}{2}} \max \left\{\left\|\overline{\bar{\Delta}}_{n}^{K}\right\|,\left\|\bar{\Delta}_{n}^{Q}\right\|,\left\|\bar{\Delta}_{n}^{K}\right\|,\left\|\bar{\Delta}_{n}^{J}\right\|\right\}\right)$, which is negligible by (A.2), Assumption 10 and (3.10), noting that $\left\|\bar{\Delta}_{n}^{Q}\right\| \leq\left\|\bar{\Delta}_{n}^{K}\right\|\left\|J_{n}^{-1}\right\|\left(\left\|\bar{\Delta}_{n}^{K}\right\|+2\left\|K_{n}\right\|\right)$.

Because $\tau_{n} \alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} q_{n}=n^{-\frac{1}{2}} a_{n}^{-\frac{1}{2}} \sum_{i=1}^{n} \alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} a_{i n}$ $u_{i}$, we will consider $n \alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} q_{n} / v_{n}=\sum_{i=1}^{n} c_{i n} u_{i}$, where $c_{i n}$ $=\alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} a_{i n} / v_{n}$ and $v_{n}=\sigma\left(\sum_{i=1}^{n}\left(\alpha^{\prime} \Psi_{n} Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1} a_{i n}\right)^{2}\right)^{\frac{1}{2}}$. $\left\{c_{i n} u_{i}, i=1, \ldots, n, n \geq 1\right\}$ forms a martingale difference sequence, by Assumption 5 . It suffices to show $\sum_{i=1}^{n} c_{i n} u_{i} \xrightarrow{d} N(0,1)$, conditional on $z_{i n}, X_{n}$, which follows by Theorem 2 of $\operatorname{Scott}$ (1973) if conditional on $z_{i n}, X_{n}$, as $n \rightarrow \infty$,
$\mathbb{E}\left(\sum_{i=1}^{n} c_{i n}^{2} u_{i}^{2} \mid u_{j}, j<i\right) \xrightarrow{p} 1$
and for all $\xi>0$
$\mathbb{E}\left(\sum_{i=1}^{n} c_{i n}^{2} \mathbb{E}\left(u_{i}^{2} \mathbf{1}\left(\left|c_{\text {in }} u_{i}\right|>\xi\right) \mid z_{i n}, X_{n}\right)\right) \rightarrow 0$,
with $\mathbf{1}(\cdot)$ denoting indicator function. The LHS of (A.9) equals 1 , while the LHS of (A.10) is bounded by
$\max _{1 \leq i \leq n} \mathbb{E}\left\{u_{i}^{2} \mathbf{1}\left(u_{i}^{2}>\frac{\xi^{2}}{\max _{1 \leq i \leq n} c_{i n}^{2}}\right)\right\} \mathbb{E}\left(\sum_{i=1}^{n} c_{i n}^{2}\right)$.
Since the $u_{i}^{2}$ are uniformly integrable, it suffices to show that $\max _{1 \leq i \leq n} c_{i n}^{2} \xrightarrow{p} 0$ as $n \rightarrow \infty$, as the last factor equals $1 / \sigma^{2}$. Now, $\max _{1 \leq i \leq n} \quad c_{i n}^{2} \leq\left\|Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1}\right\|^{2}\left\|\Psi_{n}^{\prime} \alpha\right\|^{2} \max _{1 \leq i \leq n}\left\|a_{i n}\right\|^{2} / v_{n}^{2} \leq$ $\max _{1 \leq i \leq n}\left\|a_{i n}\right\|^{2}\left\|Q_{n}^{-1} K_{n}^{\prime} J_{n}^{-1}\right\|^{2} \sigma^{-2} \bar{\eta}\left(Q_{n}\right) / n$ for large $n$, because $\sum_{i=1}^{n} a_{i n} a_{i n}^{\prime}=n \bar{J}_{n}$. This is negligible as $n \rightarrow \infty$ by Assumptions 6 , 7 and 9. The asymptotic covariance matrix exists, and is positive definite, by Lemma 3.1. The proof of consistency of the covariance matrix estimate is omitted, while the proof of Corollary 3.3 is similar, existence and positive definiteness of the asymptotic covariance matrix guaranteed by Assumptions 6 and 7.

Proof of Theorem 4.1. Note that $s_{n}=0$ for the proofs of the results in Section 4. Write
$\tilde{\theta}_{(n)}-\theta_{(n)}=\bar{L}_{n}^{-1} \overline{\bar{\Delta}}_{n}^{L}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)+\bar{L}_{n}^{-1} w_{n}$.
It is clear that

$$
\begin{equation*}
\left\|w_{n}\right\| \leq\left\|n^{-1}\left[A_{n}, X_{n}\right]^{\prime} U_{n}\right\|+\left\|n^{-1}\left[B_{n}, 0\right]^{\prime} U_{n}\right\| . \tag{A.12}
\end{equation*}
$$

Now
$\mathbb{E}\left\|n^{-1}\left[A_{n}, X_{n}\right]^{\prime} U_{n}\right\|^{2}=\mathscr{O}\left(n^{-1} c_{n}\right)$,
as in the proof Theorem 3.1, but using Assumption 11.
Write $g_{r s, i n}$ for the $(r, s)$ th element of $G_{i n}$. Though we do not assume that the $u_{i n}$ have finite fourth moment in the statement of Theorem 4.1, it is convenient to present in the current proof also some calculations that use Assumption 13 and will be useful in the proof of Theorem 4.3. In this case, the square of the second term on the RHS of (A.12) has expectation $\sum_{i=1}^{p_{n}} \mathbb{E}\left(U_{n}^{\prime} G_{i n}^{\prime} U_{n} / n\right)^{2}$ $=\mu_{4} \sum_{i=1}^{p_{n}} \sum_{j=1}^{n}\left(g_{j j, i n} / n\right)^{2}+\left(\sigma^{4} / n^{2}\right) \sum_{i=1}^{p_{n}} \sum_{j, k=1}^{n}\left(g_{j j, i n} g_{k k, i n}+\right.$ $\left.g_{j k, i n} g_{k j, i n}+g_{j k, i n}^{2}\right)=\mathscr{O}\left(p_{n} / h_{n}^{2} \max \{1 / n, 1\}\right)$, by Lemma B.2. Hence
$\left\|n^{-1}\left[B_{n}, 0\right]^{\prime} U_{n}\right\|=\mathscr{O}_{p}\left(h_{n}^{-1} p_{n}^{\frac{1}{2}}\right)$,
so that
$\left\|w_{n}\right\|=\mathscr{O}_{p}\left\{\max \left(n^{-\frac{1}{2}} c_{n}^{\frac{1}{2}}, h_{n}^{-1} p_{n}^{\frac{1}{2}}\right)\right\}$.
However, with only second moments for the $u_{i}$ we have
$\left\|n^{-1}\left[B_{n}, 0\right]^{\prime} U_{n}\right\| \leq n^{-1}\left\|\left[B_{n}, 0\right]\right\|\left\|U_{n}\right\|=\mathscr{O}_{p}\left(h_{n}^{-\frac{1}{2}} p_{n}^{\frac{1}{2}}\right)$,
by calculations used for bounding the first term on the RHS of (A.18), and so
$\left\|w_{n}\right\|=\mathscr{O}_{p}\left\{\max \left(n^{-\frac{1}{2}} c_{n}^{\frac{1}{2}}, h_{n}^{-\frac{1}{2}} p_{n}^{\frac{1}{2}}\right)\right\}$.
Also $\overline{\bar{\Delta}}_{n}^{L}=n^{-1}\left[B_{n}, 0\right]^{\prime}\left[B_{n}, 0\right]+n^{-1}\left[A_{n}, X_{n}\right]^{\prime}\left[B_{n}, 0\right]+n^{-1}\left[B_{n}, 0\right]^{\prime}$ $\left[A_{n}, X_{n}\right]$ so we have
$\left\|\overline{\bar{\Delta}}_{n}^{L}\right\| \leq n^{-1}\left\|\left[B_{n}, 0\right]\right\|^{2}+2 n^{-1}\left\|\left[A_{n}, X_{n}\right]^{\prime}\left[B_{n}, 0\right]\right\|$.
The expectation of the first term on the RHS is bounded by $\sigma^{2} \sum_{j=1}^{p_{n}} \operatorname{tr}\left(G_{j n} G_{j n}^{\prime}\right) / n \leq C p_{n} / h_{n}$, by Lemmas B. 2 and B.3. Assumption 11 and Lemma B. 1 imply that the square of the second term has expectation bounded by $\sigma^{2} \sum_{i=1}^{a_{n}} \mathbb{E}\left\|m_{i n}\right\|^{2} \sum_{j=1}^{p_{n}}\left\|G_{j n}\right\|^{2} / n^{2}=$ $\mathscr{O}\left(p_{n} k_{n}^{2} a_{n} / n\right)$, so that
$\left\|\overline{\bar{\Delta}}_{n}^{L}\right\|=\mathscr{O}_{p}\left(\max \left\{h_{n}^{-1} p_{n}, n^{-\frac{1}{2}} p_{n}^{\frac{1}{2}} k_{n} a_{n}^{\frac{1}{2}}\right\}\right)$.
From (A.11),

$$
\begin{equation*}
\left(1-\left\|\bar{L}_{n}^{-1}\right\|\left\|\overline{\bar{\Delta}}_{n}^{L}\right\|\right)\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\| \leq\left\|\bar{L}_{n}^{-1}\right\|\left\|w_{n}\right\| \tag{A.20}
\end{equation*}
$$

By (A.19) the first factor on the LHS above converges in probability to one by (4.2) and Assumption 12. The first factor on the RHS of (A.20) is $\mathscr{O}_{p}(1)$ by Assumption 12, so
$\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\|=\mathscr{O}_{p}\left\{\max \left(n^{-\frac{1}{2}} c_{n}^{\frac{1}{2}}, h_{n}^{-1} p_{n}^{\frac{1}{2}}\right)\right\}$,
by (A.15) under Assumptions 1 and 13 but
$\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\|=\mathscr{O}_{p}\left\{\max \left(n^{-\frac{1}{2}} c_{n}^{\frac{1}{2}}, h_{n}^{-\frac{1}{2}} p_{n}^{\frac{1}{2}}\right)\right\}$,
by (A.17) under Assumption 1 only. These are both negligible by (4.2).

Proof of Theorem 4.2. As in the IV case, we write

$$
\begin{aligned}
\tilde{\sigma}_{(n)}^{2}= & n^{-1} U_{n}^{\prime} U_{n}-2\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)^{\prime} w_{n} \\
& +\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)^{\prime} \overline{\bar{L}}_{n}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right) .
\end{aligned}
$$

From (A.21) and (A.15) the second term has modulus bounded by

$$
\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\|\left\|w_{n}\right\|=\mathscr{O}_{p}\left(\max \left\{n^{-1} c_{n}, h_{n}^{-2} p_{n}, n^{-\frac{1}{2}} h_{n}^{-1} p_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}}\right\}\right)
$$

while the modulus of the third term is bounded by

$$
\begin{aligned}
& \left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\|^{2}\left(\left\|\bar{L}_{n}\right\|+\left\|\overline{\bar{\Delta}}_{n}^{L}\right\|\right) \\
& \quad=\mathscr{O}_{p}\left(\max \left\{n^{-1} c_{n}, h_{n}^{-2} p_{n}, n^{-\frac{1}{2}} h_{n}^{-1} p_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}}\right\}\right)
\end{aligned}
$$

using (A.19), (A.21) and Assumption 8. We conclude that
$\tilde{\sigma}_{(n)}^{2}-\sigma^{2}=\mathscr{O}_{p}\left(\max \left\{n^{-1} c_{n}, h_{n}^{-2} p_{n}, n^{-\frac{1}{2}} h_{n}^{-1} p_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}}\right\}\right)$.
This is negligible by (4.4).
Proof of Theorem 4.3. With $\alpha$ any non-null $q \times 1$ vector, write

$$
\begin{align*}
\tau_{n} \alpha^{\prime} \Psi_{n}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)= & \tau_{n} \alpha^{\prime} \Psi_{n} \bar{L}_{n}^{-1}\left(\overline{\bar{\Delta}}_{n}^{L}\left(\tilde{\theta}_{(n)}-\theta_{(n)}\right)+\bar{\Delta}_{n}^{L} L_{n}^{-1} w_{n}\right) \\
& +\tau_{n} \alpha^{\prime} \Psi_{n} L_{n}^{-1} w_{n} . \tag{A.24}
\end{align*}
$$

We first show that first term on the RHS of (A.24) is negligible in probability. It has modulus bounded by $C \tau_{n}\left\|\Psi_{n}\right\|\left\|\bar{L}_{n}^{-1}\right\|$ $\left(\left\|\overline{\bar{\Delta}}_{n}^{L}\right\|\left\|\tilde{\theta}_{(n)}-\theta_{(n)}\right\|+\left\|\bar{\Delta}_{n}^{L}\right\|\left\|L_{n}^{-1}\right\|\left\|w_{n}\right\|\right)=\mathscr{O}_{p}\left(\max \left\{c_{n}^{\frac{1}{2}}, n^{\frac{1}{2}} p_{n}^{\frac{1}{2}} /\right.\right.$ $\left.h_{n}\right\} \max \left\{p_{n} / h_{n}, p_{n}^{\frac{1}{2}} k_{n} a_{n}^{\frac{1}{2}} / n^{\frac{1}{2}},\left\|\bar{\Delta}_{n}^{L}\right\|\right\}$ ), by (A.15), (A.19), (A.21) and Assumption 12. This is $\mathscr{O}_{p}\left(\max \left\{p_{n}^{\frac{1}{2}} k_{n} a_{n}^{\frac{1}{2}} c_{n}^{\frac{1}{2}} / n^{\frac{1}{2}}, p_{n} c_{n}^{\frac{1}{2}} / h_{n}, p_{n} k_{n}\right.\right.$ $\left.a_{n}^{\frac{1}{2}} / h_{n}, n^{\frac{1}{2}} p_{n}^{\frac{3}{2}} / h_{n}^{2}\right\}$ ), (using Assumption 15) which is negligible by (4.5) because

$$
\begin{aligned}
& p_{n} k_{n}^{2} a_{n} c_{n} \leq C\left(p_{n}^{3} k_{n}^{4}+p_{n}^{2} k_{n}^{5}\right), \quad p_{n}^{2} c_{n} \leq C p_{n}^{3} k_{n}^{2}, \\
& n p_{n}^{3}=n^{2} p_{n}^{2} n^{-1} p_{n} \\
& p_{n}^{2} k_{n}^{2} a_{n}=p_{n}^{3} k_{n}^{2}+p_{n}^{2} k_{n}^{3}=n p_{n}\left(n^{-1} p_{n}^{2} k_{n}^{2}+n^{-1} p_{n} k_{n}^{3}\right) .
\end{aligned}
$$

The second term on the RHS of (A.24) is

$$
\begin{align*}
\tau_{n} \alpha^{\prime} \Psi_{n} L_{n}^{-1} w_{n}= & \tau_{n} \alpha^{\prime} \Psi_{n} L_{n}^{-1} n^{-1}\left[A_{n}, X_{n}\right]^{\prime} U_{n} \\
& +\tau_{n} \alpha^{\prime} \Psi_{n} L_{n}^{-1} n^{-1}\left[B_{n}, 0\right]^{\prime} U_{n} \tag{A.25}
\end{align*}
$$

The modulus of the second term on the RHS of (A.25) is bounded by $\tau_{n}$ times
$\|\alpha\|\left\|\Psi_{n}\right\|\left\|\bar{L}_{n}^{-1}\right\|\left\|n^{-1}\left[B_{n}, 0\right]^{\prime} U_{n}\right\|$.
The second factor on the RHS above is $\mathscr{O}\left(a_{n}^{\frac{1}{2}}\right)$, the third is $\mathscr{O}_{p}(1)$ by Assumption 12, and the fourth is $\mathscr{O}_{p}\left(p_{n}^{\frac{1}{2}} / h_{n}\right)$ by (A.14). Therefore (A.26) is $\mathscr{O}_{p}\left(p_{n}^{\frac{1}{2}} a_{n}^{\frac{1}{2}} / h_{n}\right)$ and so the second term on the RHS of (A.25) is $\mathscr{O}_{p}\left(n^{\frac{1}{2}} p_{n}^{\frac{1}{2}} / h_{n}\right)$. Under (4.5) this is $o_{p}(1)$, so we need to compute only the asymptotic distribution of the first term on the RHS in (A.25), which we write as $\sum_{i=1}^{n}$ $f_{i n} u_{i}$ with $f_{\text {in }}=\alpha^{\prime} \Psi_{n} L_{n}^{-1} t_{i n} / d_{n}$ and $d_{n}=\sigma\left\{\sum_{i=1}^{n}\left(\alpha^{\prime} \Psi_{n} L_{n}^{-1} t_{i n}\right)^{2}\right\}^{\frac{1}{2}}$. As in the proof of Theorem 3.3, $\max _{1 \leq i \leq n} f_{i n}^{2} \leq n^{-1} \max _{1 \leq i \leq n}\left\|t_{i n}\right\|^{2}$
$\left\|L_{n}^{-1}\right\|^{2} \sigma^{-2} \bar{\eta}\left(L_{n}\right)$, for large enough $n$. This is negligible as $n \rightarrow \infty$ by Assumptions 8, 12 and 14. The asymptotic covariance matrix exists, and is positive definite, by Assumptions 8 and 12. The proof of consistency of the covariance matrix estimate is omitted.

## Appendix B. Technical lemmas

Lemma B.1. Let Assumptions 3 and 4 hold. Then $\left\|G_{i n}\right\|_{R}$ and $\left\|G_{i n}^{\prime}\right\|_{R}$ are uniformly bounded for all $i=1, \ldots, p_{n}$ and $n \geq 1$.
Proof. For any $i=1, \ldots, p_{n},\left\|G_{i n}\right\|_{R}=\left\|S_{n}^{-1} W_{i n}\right\|_{R} \leq\left\|S_{n}^{-1}\right\|_{R}$ $\left\|W_{i n}\right\|_{R} \leq C$ where the last inequality follows from Assumption 4. The claim for $G_{i n}^{\prime}$ follows similarly.

Lemma B.2. Let Assumptions 2-4 hold. Then, for all $i=1, \ldots, p_{n}$, the elements of $G_{i n}$ are uniformly $\mathscr{O}\left(h_{n}^{-1}\right)$ as $n \rightarrow \infty$.
Proof. Denote by $w_{j, i n}^{\prime}$ the $j$ th row of $W_{i n}$. Then the $(j, k)$ th element of $G_{i n}$ is given by $w_{j, i n}^{\prime} S_{n}^{-1} e_{k, n}$, where $e_{k, n}$ is the $n \times 1$ vector with unity in the $k$ th position and zeros elsewhere. Then $\left|w_{j, i n}^{\prime} S_{n}^{-1} e_{k, n}\right| \leq$ $\left\|w_{j, i n}\right\|_{R}\left\|S_{n}^{-1}\right\|_{R}\left\|e_{k, n}\right\|_{R}=\mathscr{O}\left(h_{n}^{-1}\right)$.

Lemma B.3. Let Assumptions $2-4$ hold. Then, for all $i=1, \ldots, p_{n}$, the elements of a product consisting of any finite number of the $G_{i n}$ or their transposes are uniformly $\mathscr{O}\left(h_{n}^{-1}\right)$ as $n \rightarrow \infty$.

Proof. Similar to proof of Lemma B.2.

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